

UHSAP - A POL FOR ANALYSIS
OF LINEAR AND QUASI-LINEAR SYSTEMS

A Thesis
Presented to
the Faculty of the Department of Electrical Engineering
University of Houston

In Partial Fulfillment
of the Requirements for the Degree
Master of Science in Electrical Engineering

by
Srirammohan S. Beltangady

December 1971

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ABSTRACT

This thesis discusses the addition of a language processor and the modifications made in the output routines of ECAP to extend its capability to analyze problems in other linear and quasi-linear time-invariant systems. A new language called UHSAP is the desired extension.

INTRODUCTION

ECAP is a versatile problem oriented language for analysis of electronic networks. It also has capabilities for sensitivity analysis and worst case solutions. Since the basic algorithms to analyze electronic networks can be effectively used to analyze other linear and quasi-linear time-invariant systems, ECAP algorithmic units can perform the analysis problems for other systems.

This has been achieved in UHSAP which is an extension of ECAP. The data structure of UHSAP has been designed to accept the commands and directives in other systems. This addition of a relatively small unit to ECAP has considerably extended the capability of ECAP. The approach for translating the commands and data from UHSAP to ECAP has been that of character manipulation. Valid characters are identified and replaced to generate an object code in ECAP.

The package has been implemented effectively on OS 360/Model 44 and may, with minor changes, be implemented on other comparable computer systems.

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CHAPTER I

PROBLEM ORIENTED LANGUAGES

Webster's dictionary defines a language as a systematic means of communicating ideas or feelings by the use of conventionalized signs, gestures or marks and understood by a considerable community. The number of variables in this definition itself gives a fairly good idea of the possible number of languages human beings use. Translation of ideas from one language into another has been of interest since a long time. With the advent of machines as an aid to contribute towards the efficiency of human activities, machine translation of languages has drawn considerable attention. In spite of the amount of research and money spent on machines capable of translating one language into another, the attempts have met with little success for obvious reasons such as the syntactical and semantical ambiguity of languages. Even with such simple redefinition of a language as a series of symbols representing ideas, the simplest conceivable written language having one symbol per idea, Richens and Booth have not succeeded in the objective of machine translation.

It is at this point that Artificial Languages differ from the earlier set of so called Natural Languages. Because of their inherently simple grammar and the concise, unambiguous meanings, artificial languages have led to an effective

machine translation among themselves. Programming languages which facilitate our communication with computers, both concisely and precisely, fall in this category.

Higher level programming languages are characterized by ease of understanding, machine independence, similarity with a natural language and a flexible sentence structure as against more complex and unintelligible lower level languages such as machine language. Higher level languages differ among themselves not only on the level their intelligibility but also in the general areas of their applicability. Procedural languages like FORTRAN and PL/I are useful for a wide range of problems in numerical analysis and scientific computations. Nevertheless, a demand for their employment in other areas has led to modifications and subsequently to more complexity in their syntax and vocabulary.

Problem oriented languages, or POL's , as they are commonly called, are more restricted in their usage than procedural languages. They are specifically designed for solving specific types of problems in a relatively narrow field. This loss of generality is compensated by their simplicity and the ease with which they may be learned and used. A typical POL is easy to learn, has simple syntax, has a vocabulary normally conforming with that in the application area and needs a minimum programming effort on the part of the user. Some POL's allow the user to add the necessary routines

in the procedural language to aid the problem description and its solution, thus increasing their flexibility. The commands and directives in a POL, which is normally written in a procedural language, are interfaced in such a way as to allow the addition of extra commands in a POL. Each command or directive causes the appropriate routines to be called. The routines of a POL can often be divided into three basic parts.

The first part is the language processor. This is normally a translator which produces an appropriate code for the commands in the POL. The language being translated to is called the object language. An object language may be either a procedural language or another POL. A translator, typically, reads a statement, checks it for validity and meaning, and then produces the corresponding object code. A good POL translator also detects the syntactical validity of a statement and points out any errors with suitable error messages. The advantage of having a translator is the saving in the core space required by the program. Once the object code for the problem is generated, this segment of the program no longer needs to reside in the core and to occupy the space, till execution is completed.

The second part consists of a set of arithmetic expressions, algorithms and analytical routines normally used for the solution of the problems in the area. Often, this unit is quite complex and it is this complexity from the user's

point of view that usually justifies the need for a POL.

The third part is a set of output routines. This is responsible for printing out the requested output in specific formats. The degree of control a user has over the flexibility of the formats and matter to be printed differs from one POL to another.

In Figure 1.1 the general structure of a typical problem oriented language is shown.

STRUCTURE OF A POL

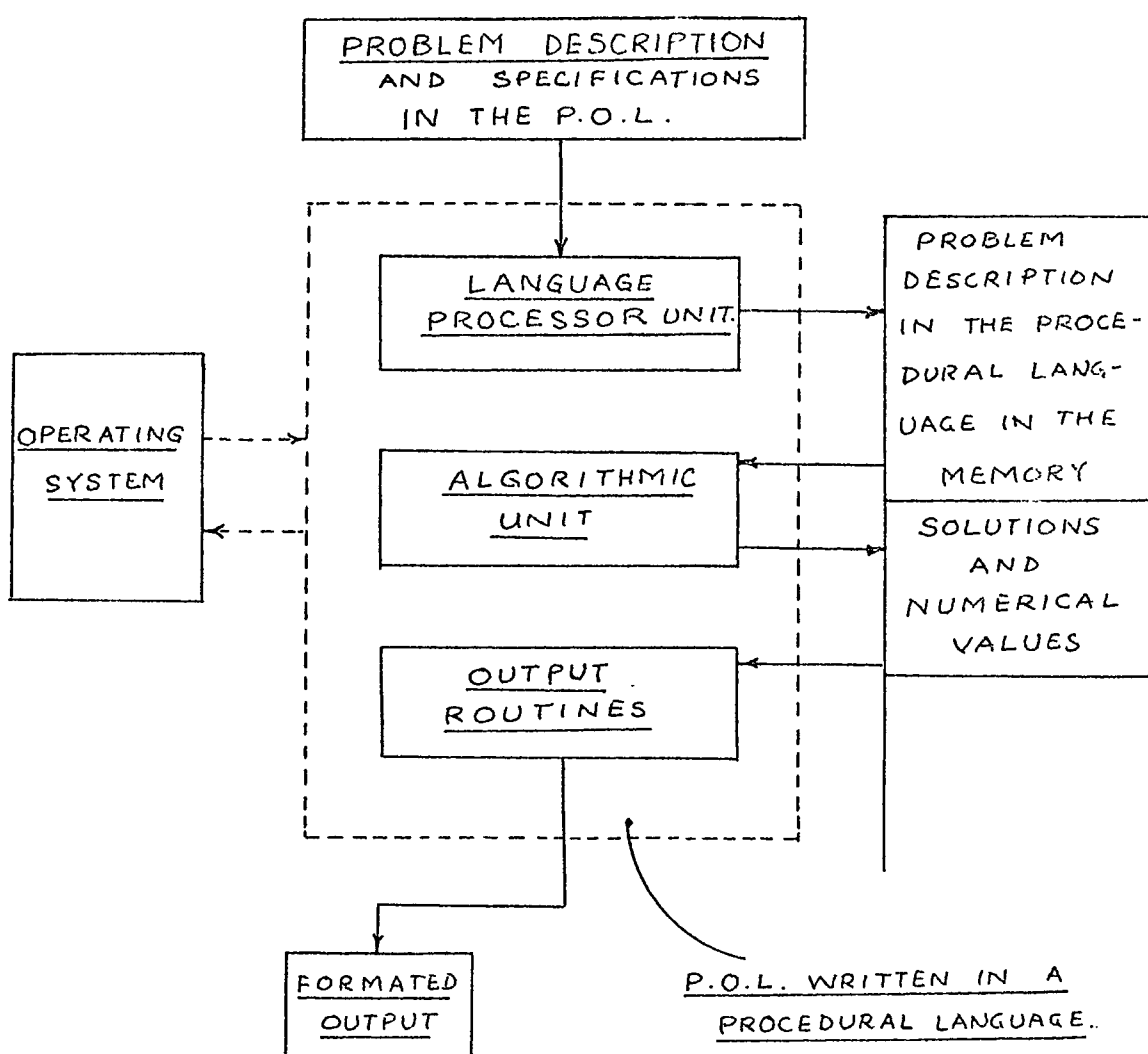


Fig. 1.1

CHAPTER II

ANALYSIS OF SYSTEMS USING ECAP

Analysis, or prediction of performance, of a physical system has been of importance to designers as well as to users. Whereas systems with distributed type parameters can be analyzed by solving partial differential equations, those with lumped parameters can be analyzed by solving ordinary differential equations. These equations, called the mathematical model of the system, have constant coefficients for each term in case of linear time-invariant systems. Quasi-linear systems are those non-linear systems whose behavior can be represented by a piecewise linear approximation. Mathematical models of simple linear time-invariant systems have the form as in Equation 2.1.

$$A \frac{dx}{dt} + Bx + C \int x \, dt = 0 \quad (2.1)$$

Equations which have the same form are called analogous equations and the systems they represent are called analogous systems. Because of the similarity of their mathematical models, the following time-invariant linear systems form examples of analogous systems:

- A. Mechanical Translational
- B. Mechanical Rotational

- C. Electrical
- D. Acoustical
- E. Thermal.

System analogs, their prototype variables and their conventionalized notations are listed in Table 2.1.

The mathematical model of a physical system is generally derived from its diagram for further analysis, but there is an additional type of model called the equivalent circuit, which resembles an electrical network. The advantage of this form of representation is that it can be easily analyzed using the already developed techniques for circuit analysis, resulting in inherent economies in the solution procedures and algorithms. A number of large programs and POL's have been written to accomplish the electronic circuit analysis. ECAP is a POL capable of performing DC, AC and transient analyses of electrical networks. The data structure of ECAP, however, allows only the direct description of electrical networks. Hence, the use of ECAP to analyze other systems would normally require drawing an equivalent circuit prior to describing it to ECAP. This drudgery has been eliminated by UHSAP.

UHSAP, an acronym for University of Houston System Analysis Program, is an extension of ECAP with the capability to analyze problems in other linear and quasi-linear analogous systems. It uses ECAP's main algorithmic and analytic routines.

TABLE 2.1*

System	Elect- rical	Mech. Transl. .	Mech. Rota.	Acous- tical	Thermal
Proto- type					
w	e	v	ω	p	t
u	i	f	τ	u	q
α	L	$\frac{1}{K}$	$\frac{1}{K}$	M	-
β	R	$\frac{1}{B}$	$\frac{1}{B}$	R	R
γ	$\frac{1}{C}$	$\frac{1}{M}$	$\frac{1}{J}$	$\frac{1}{C}$	$\frac{1}{C}$

*Adapted from Linear Circuit Analysis by Paskusz and Bussel.

UHSAP is different from a conventionalized POL in the sense that the object language of its language processor is another POL, viz ECAP. The three parts of UHSAP are language processor, ECAP routines and output routines, where ECAP routines themselves can be sub-divided into three parts as shown in Chapter I.

The language processor accepts the commands and converts them into corresponding ones in ECAP. To make the programming and understanding of the language easier, the data structure of UHSAP has been maintained the same as that of ECAP. Generally, the user will have to follow the following steps to analyze a problem in any one of the analogous systems mentioned earlier:

1. Draw a topological diagram of the system.
2. Identify nodes and branches.
3. Assume positive directions of flow variables.
4. Specify the type of system, type of analysis and output desired.
5. Describe the topology of the diagram to the program in accordance with valid UHSAP syntax and variables.

Output routines have been written to print out the desired solutions in corresponding system variables and appropriate formats.

The general structure of UHSAP is shown in Figure 2.1.

STRUCTURE OF UHSAP

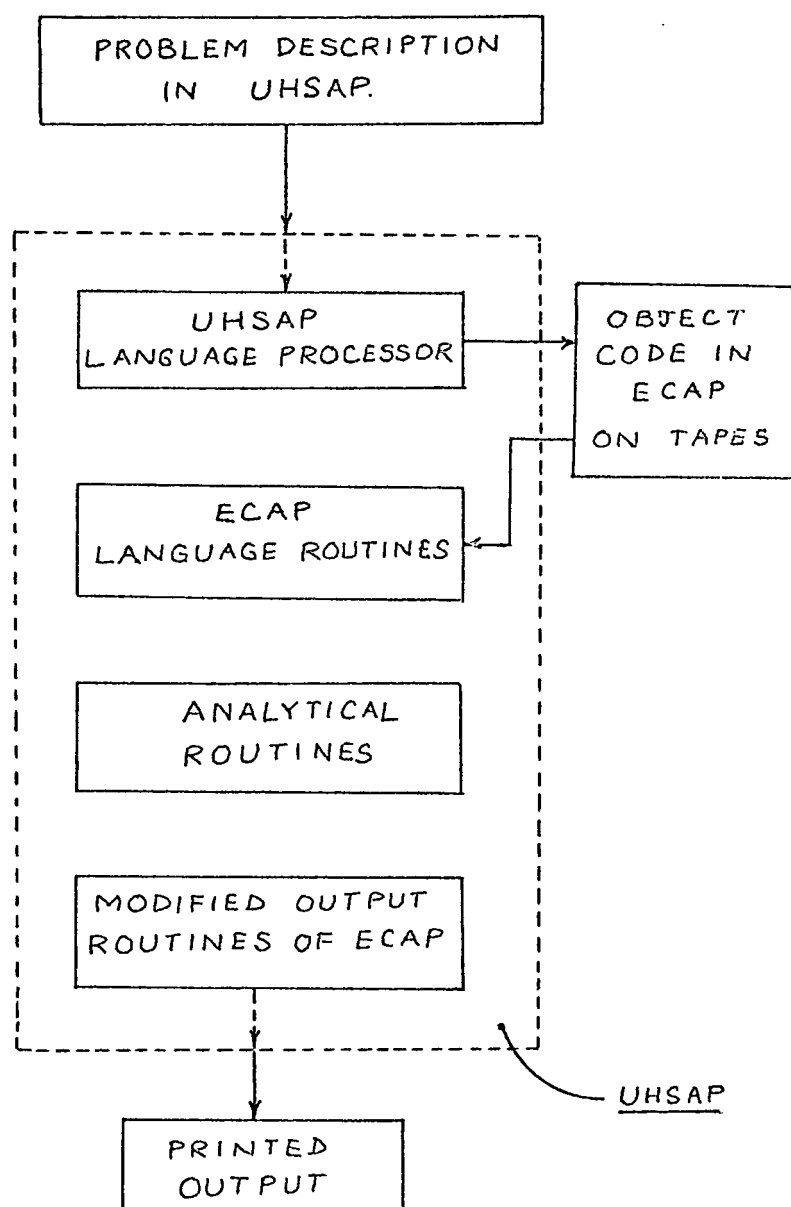


Fig. 2.1

CHAPTER III

A USER'S GUIDE TO THE LANGUAGE

The UHSAP input language is the primary communication link between the user and the analysis program, viz ECAP. It provides the user with a means of describing his topological diagram in familiar terms and notations to the program as well as a means of controlling the type of analysis to be performed. With minor restrictions, all data may appear in any order and in free form.

General Properties of Input Language

All input statements are entered on cards in columns 1 through 72. Blanks are generally ignored and may be inserted for clarity and convenience. Exceptions are noted below. Each card may have only one statement, ended with a semicolon (;). By default, the semicolon is assumed at column 72 and a diagnostic message is printed. Problems are described to the program with 6 different types of cards:

1. System identifier card
2. Data card
3. Solution control card
4. Output specification card
5. Command card
6. Comment card

Numerical values are accepted by the program in any one of the following familiar forms: signed integer, decimal and exponential notation.

The following are examples of valid numbers:

10	20.7	20 E-7
+15	+.7	+.5 E+16
-7	-100.	-7.8 E15

Description of Input Statements

A. System identifier card:

This card must be the first card of the input. It must start in the first column and specify the system. Only the first two characters are identified by the program and must not be blanks. Any text may appear in columns 3 through 72. Valid system identifier cards are as follows:

└ Column 1
 ↓
ELECTRICAL

MECHANICAL

ROTATIONAL

ACOUSTICAL

THERMAL

B. Data card

Data cards contain information directly related to the problem such as the topology of the system, the parameter values, the tolerances, the phase angles, etc. They are either

of branch type (*B*-Card), of dependent source type (*T*-Card), or of direction sensing type (*S*-Card). Mutual inductance type (*M*-Card) cards are also available in the electrical system.

Each card has two data fields: columns 1 through 5 and 7 through 72. A non-blank character in the sixth column indicates that the card is the continuation of the one preceding it.

1. The first field specifies the type of data card with the serial number of that type. The general format is Xnn starting in the first column, where X is either B , T , S , or M and nn is the serial number.

2. The second field has one or more data subgroups, each separated by a comma (,) from the preceding one. Allowable data subgroups are as follows:

a. Required topological description: These have different forms for different data cards.

1. In case of *B*-Cards, this field indicates the topology of the branch and has the form:

$$N(n_1, n_2)$$

where n_1 is the initial node number and n_2 is the final node number.

2. In case of *T*-Cards, this has the form:

$$B(b_1, b_2)$$

where b_1 is the branch of the controlling branch¹ and b_2 is the branch number of the assigned branch.¹

3. In case of *S*-Cards,¹ this has the form:

$$B = b_s, (b_1, b_2, \dots, b_n), x$$

where b_s is the branch number in which the sensing element lies. Parameter values of elements in b_1, b_2, \dots, b_n are affected by the direction of flow variable in b_s . The x shows initial sense of the sensing element.

- b. Required element: Each *B*-Card must contain one and only one passive element identification. Valid names for elements in different systems are tabulated in Appendix B (Table 1). On *B*-Cards, this subgroup has the form:

$$X = v$$

where X is the element name and v is the numerical value. For *T*-Cards, this subgroup specifies the ratio or the relations between the elements in

¹For elaborate discussions about *T*-Cards and *S*-Cards see Ref. 3.

the controlling branch and the controlled branch.

- c. Optional element: To specify the value of a source in a branch, this subgroup with a general form

$$X = p$$

where X is the valid source symbol listed in Appendix B (Table 2) and p is its numerical value.

- d. Initial condition: For transient analysis, specification of initial condition of an element is required and is given by using valid source element name followed by either 0 or 1 and value specified with an equal sign and a number.

3. Another type of data cards is the time dependent source card. These are of the following general form:

$\begin{array}{c} \text{column 1} \\ \downarrow \\ X \text{ nn} \quad (k), p_0, p_1, p_2, \dots, p_n \\ \uparrow \\ \text{column 7} \end{array}$


where X is the valid source symbol and nn is the branch in which it is present. The number k shows the integer number of time steps between successive entries of source magnitudes $p_0, p_1, p_2, \dots, p_n$ which are equally spaced in time. Figure 3.2 shows image of a source card.

C. Solution control card:

There are two types of solution control cards, both types


start in column 7.

1. The first one contains information directly related to the analysis for the system such as time step, frequency, final time, etc. General format of this type of card is:


 column 7
 SPECIFICATION = p

where p is the numerical value of the valid specifications listed in Appendix B (Table 3).

2. The second type contains the specifications of calculations to be made, such as sensitivity analysis, worst case analysis, etc. and has the form:



 column 7
 SPECIFICATION

In both cases, however, only the first two characters of the specification are identified by the language processor. Therefore, blanks are not permitted in columns 7 and 8 of a valid specification card.

Figure 3.3 shows an image of solution control cards.

D. Output specification card:

This allows user to select the blocks of output which he would like to have printed. General format of this card is:


 column 7
`PRINT, v1, v2, ..., vn`

where symbols v_1, v_2, \dots, v_n are the valid output symbols the user may specify. These have been listed in Appendix B (Table 4). Each block is separated by a comma (,) from the preceding one. Here, too, only the first two characters of each block are identified, so no blanks are permitted in the first two characters of any block. Figure 3.3 shows the image of possible output specification cards.

E. Command card:

This is used to specify the type of analysis desired, or to call for a parameter modification solution, or to start the execution, or to signal the end of a job. Valid commands for different systems are listed in Appendix B (Table 5). Command cards are entered starting in column 7. Only the first two characters are identified by the language processor and hence columns 7 and 8 may contain no blanks. Any text may follow in columns 9 through 72.

F. Comment card:

Beginning with a 'C' in the first column, any text may appear in columns 2 through 72. This is not processed by the program but appears in the listing of the problem. Figure 3.4 shows some images of command cards and comment cards.

COMMAND CARD		FORTRAN																									
C		EXAMPLES OF SOLUTION																									
C		CONTROL CARDS AND																									
C		OUTPUT SPECIFICATION CARDS																									
C		FREQUENCY=1.2E3;																									
		TIME STEP=5E-3;																									
		SENSITIVITY ANALYSIS;																									
C		PRINT, FORCES, VELOCITIES;																									
C		PRINT, ANGULAR VELOCITIES, TORQUE;																									

Figure 3.3

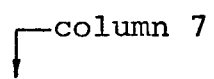
C		THIS IS A COMMENT CARD SINCE																									
C		THE FIRST COLUMN HAS 'C'.																									
C		COMMAND CARD EXAMPLES																									
C		DYNAMIC ANALYSIS;																									
		EXECUTE;																									
		MODIFY;																									

*A standard card for IBM execution of the program is shown in Figure 3.4.

Figure 3.4

Input Data Modification

The command *MODIFY* can be used for AC or DC type analysis problems and allow the user to repeat the preceding analysis with the modified values of parameters as desired. It requires the addition of only the new parameter value specification following the *MODIFY* card. The user cannot, however, change the topology of the circuit with a *MODIFY* card. The *MODIFY* feature is particularly helpful for frequency analysis, where with the card



 FREQUENCY = $p_1(p_2) p_3$

the calculations can be repeated starting with frequency p_1 , incremented logarithmically by a factor of p_2 till the final frequency p_3 is reached or exceeded.

Restrictions

This section is intended to point out the restrictions and minimum requirements which pertain to the input language of UHSAP. The restrictions exercised by ECAP are also effective in case of UHSAP because of the inherent similarity between the data structure of both. UHSAP can analyze problems with 50 nodes and 200 branches as maximum, in addition to other size requirements and restrictions of ECAP. As a minimum requirement, a UHSAP job must contain the following input cards:

1. System identifier card
2. Command card (specifying the analysis desired)
3. Data cards
4. Output specification card
5. Command card (signalling the start of execution)
6. Command card (end of job)

In addition, in case of AC type analysis to be performed, a solution control card specifying the frequency of the source must be entered and for transient type analysis, time step specification has to be made. In both cases, numerical values of frequency or time step cannot be zero. UHSAP assumes values for some of the input variables unless they are specified (for more details, please see Reference No. 3, pages 31 and 32). Nodes must be numbered consecutively from 1, with 0 assigned to the ground or to the frame of reference. All branches must be numbered consecutively from 1, but may be in any order.

The user is required to restrict himself to consistent system of units in specifying data. Reference No. 3 will serve as a valuable guide to the interested users of UHSAP. Valuable modeling techniques for analysis of quasi-linear systems will be found in the Reference numbers 2 and 3.

Example

Let us consider that we have to perform the dynamic

analysis of the mechanical translational system shown in Figure 3.5.

Our first step will be to identify nodes and to assign some positive directions of force flow for each branch. Nodes are identified by those lumped elements of the system where the velocity can be determined. So, ① and ② identify two nodes with ③ at the frame of reference. Branches are indicated as $\overrightarrow{[n]}$ with n as the assigned number and the arrow pointing in the assumed direction of force flow in that branch. The UHSAP coding of the problem with desired output blocks for velocities at both the nodes and forces developed in all the elements is shown in Figure 3.6.

For the discussion about the choice of time step to be selected please see References 3 and 4.

This example shows the general structure of a typical UHSAP problem. Appendix D includes more sample problems and the analysis results from UHSAP.

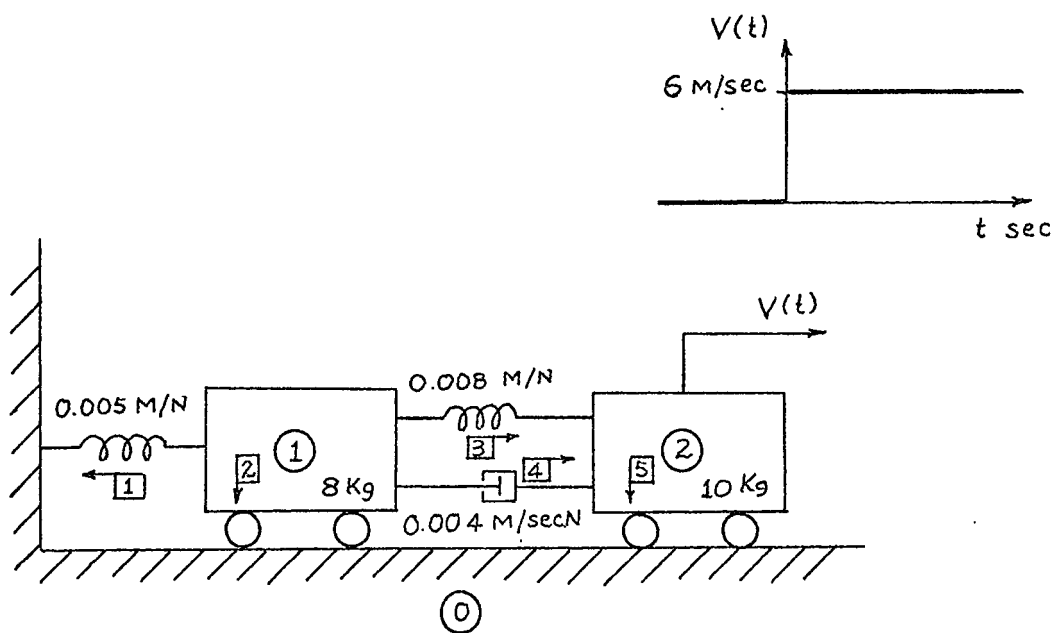


Fig. 3.5

CHAPTER IV

DESCRIPTION OF UHSAP LANGUAGE PROCESSOR AND OUTPUT ROUTINE MODIFICATIONS

This chapter is devoted to the description of routines added to accomplish the translation of UHSAP coding into valid ECAP coding. These routines, their names, brief summary of each and the flowcharts are shown in Appendix A.

Language Processor

For the purpose of simplicity and clarity, all the variables are defined to be integers in the language processor. The MAIN program puts in a call to the ULANG routine. Since the valid characters are system dependent, ULANG first calls the SYSID routine, which reads the first card and sets the value of MYSYS accordingly. In case of invalid system identifiers, the program terminates, giving an appropriate error message. If the system is identified to be the electrical system, MYSYS is set to one and control is returned to MAIN, since no translation of coding is required.

ULANG then calls subroutine READER to read the new card image into array S and to set the pointer DOL to one and the statement delimiter flag SEND to zero. The DUMP routine prints out the source image that has been entered in S.

The first step in the processing of data is to determine whether the new card is a comment card, in which case the READER is called in again to accept the next image. Function BLANK checks if the first six columns of the new image are blanks. If so, then the card belongs to either command type or solution control type or output specification type.

To process these types of cards ULANG calls routine TCOM. Valid characters for the system are initialized by the appropriate MYSYS value in the work array STAB and the work vector SCHAR. Function SELECT compares characters in columns 7 and 8 against valid two-character identifiers in STAB and sets PTR to the corresponding value. Invalid characters are identified by an error message through routine DIAG which prints out the characters in its argument vector. If the command is an end card, flag PEND is set to one which in effect transfers the control back to MAIN. Routine PUT chooses appropriate ECAP characters from the initialized array HTAB and transfers them to the output array NWORDS. In case of command cards, the control is transferred to ULANG for taking in a new card image through READER, since the text following column 8 is unimportant.

For solution control cards, characters upto the statement delimiter are important. Therefore, the function FIND is invoked to determine the column number in which the semicolon lies and all the characters upto that column are transferred

as they are to the output vector NWORDS through routine RETAIN. Function FIND sets the column value to 72 in case the semi-colon is not present, but gives a diagnostic message through DIAG. The control is then returned to ULANG.

For output specification cards, ULANG calls the routine TRBLOK which translates the valid output block indicators. First FIND sets the value of LAST to the column number of the statement delimiter. Then it sets COMMA by updating the scanning pointer DOL to the column number where a comma lies. The comma separates a block from the one preceding it. The updating of scanner is stopped when the value of DOL exceeds that of LAST and the control is returned to ULANG by setting SEND equal to one. The routine RETAIN transfers all the characters from the current value of DOL to COMMA as they are to output vector NWORDS. Function SELECT checks next two characters in S for their validity as block indicators by comparing them against those in STAB. PUT transfers the appropriate ones to NWORDS from array HTAB.

ULANG then calls function SOLN to process the data type cards. Function LOCATE sets the value of CTYPE by comparing the character in the first column of the card image against the valid ones, initialized in the work vector SCHAR. If invalid characters are present, proper diagnostic is given and control is returned to ULANG by making SEND value equal to

one.

For *T*-cards, the procedure is different from the one described above. When a letter is found, it is checked whether the next column has a letter too and if so, whether characters equivalent to the transconductance identifier or whether the consecutive four have current gain equivalent identifier. Function ICHK compares valid characters with those in vectors BETA and GM. Subroutine PLACE transfers appropriate ones from vectors HBETA and HGM to NWORDS.

Everytime the control is transferred to ULANG from these translating routines, value of SEND is checked. If it is one, the image in NWORDS is written on the scratch tape which is used as data file 1. Value of PEND is also checked to see if it is one, in which case the tape is rewound and the control is returned to MAIN. Flag for the validity of the problem is set to zero initially. But in case of invalid characters and such fatal errors its value is changed to one. The MAIN terminates the job by giving an appropriate error message if the value of the validity flag, IABORT, is one when the control is back to MAIN.

The MAIN calls ECA, which reads the input from data file 1 on the tape if MYSYS value is different from one and from the card reader if MYSYS value is one, i.e., if the system is specified to be electrical.

This completes the description of the language processor and the part it plays in the translation. The requested analysis is performed by appropriate routines in ECAP.

Output Routine Modification

Changes were made in ECAP routines ECA21, ECA51 and PRINT2. These are the routines which print out most of the results. The changes were of the same nature in all these routines. All the formats that print system dependent information are stored for each of the systems with different format numbers. The variable MYSYS selects an appropriate format for printing.

Appendix C shows the program listing for the language processor and also the changes that need to be made in some ECAP routines to effectively implement UHSAP.

CHAPTER V

ANALYSIS AND CONCLUSIONS

The objective of extending the capabilities of ECAP to analyze other linear and quasi-linear systems is adequately met by UHSAP. The general performance of the package is satisfactory. Fatal errors in the problem coding and specification, such as illegal characters and invalid parameters are trapped successfully by the language processor. The job gets terminated if the fatal errors are detected and appropriate error messages are printed. If the errors are not fatal, the generator object code gets processed by ECAP language routines and analyzed.

The advantage of using the ECAP data structure for UHSAP, besides the economics in computer time for language processing, is the ease with which someone conversant with ECAP can use UHSAP in the analyses of other systems. The user's manual of ECAP [3] or that of UHCAP [5] (University of Houston Circuit Analysis Program) will be of help to a new user in familiarizing himself with the general usage of UHSAP.

One of the major difficulties in implementation of UHSAP was the size limitation of the operating system. IBM 360/Model 44 barely manages to hold the ECAP modules even

with an extensively complicated overlay structure. Addition of routines made it increasingly difficult to accommodate the modules in the core. In addition to storing this new language processor unit in a different overlay segment, two arrays in main ECAP routines were reduced in size. This reduced the capability of ECAP to analyze circuits from a maximum of 50 nodes to 20 nodes, but made enough room for the additional routines. The package now runs efficiently on the system.

This language will also be implemented on the UNIVAC 1108 system. Because of the large core size available on the 1108, it is felt that the major hurdle will be done away with and we will be able to accommodate circuits having up to 50 nodes.

Appendix D shows UHSAP applied to a few sample problems.

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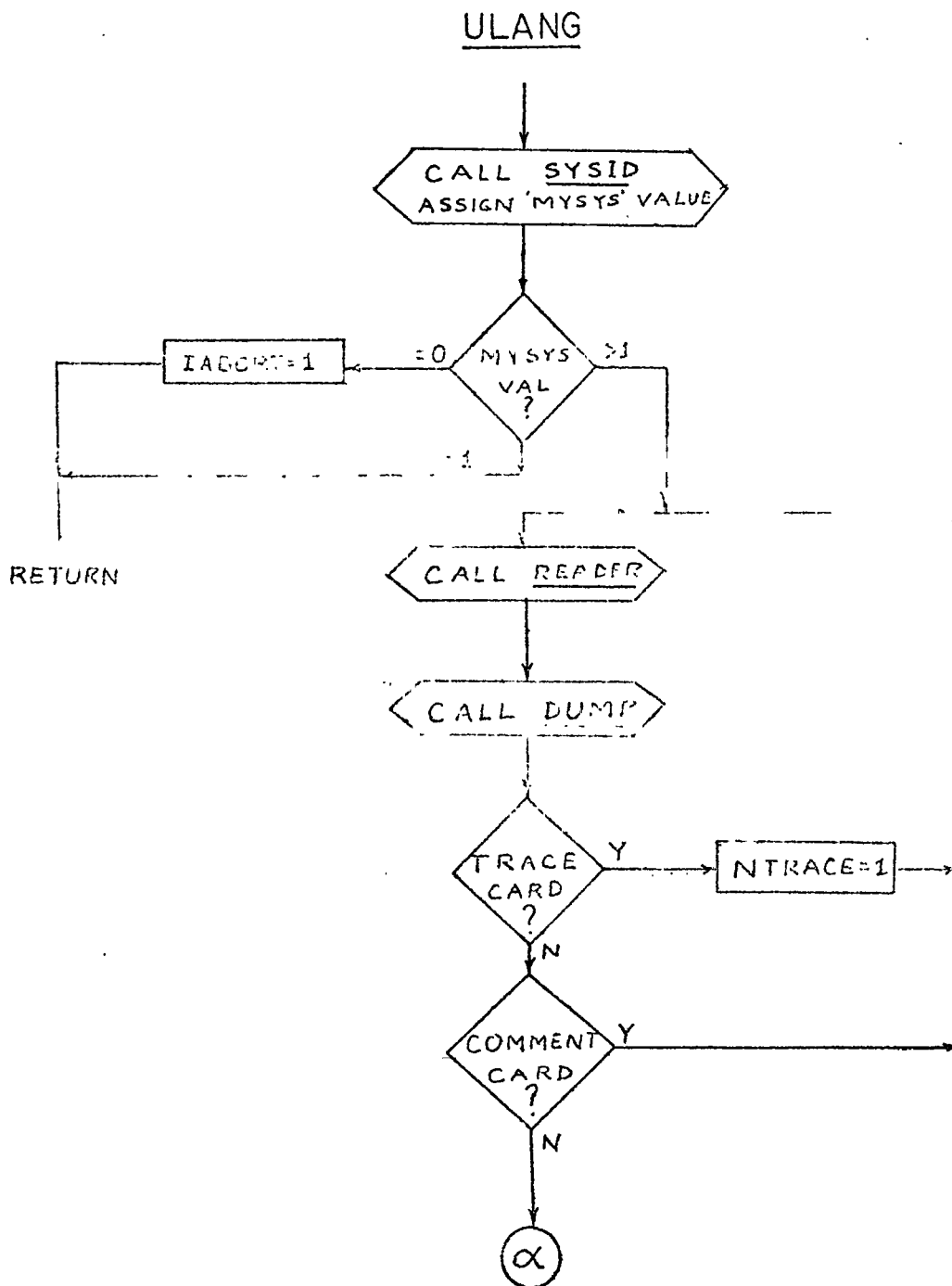
APPENDIX A

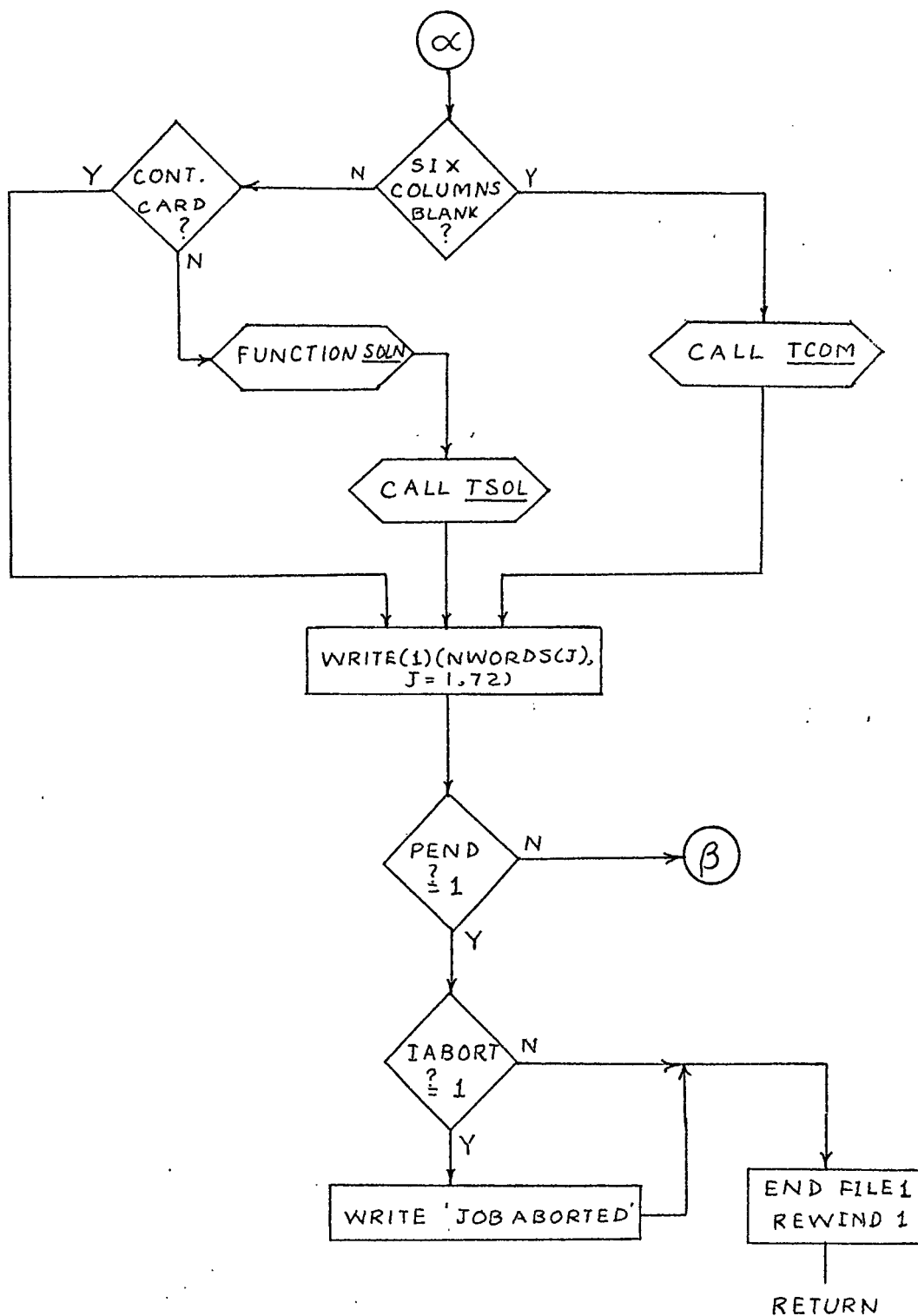
LANGUAGE PROCESSOR ROUTINES AND FLOWCHARTS

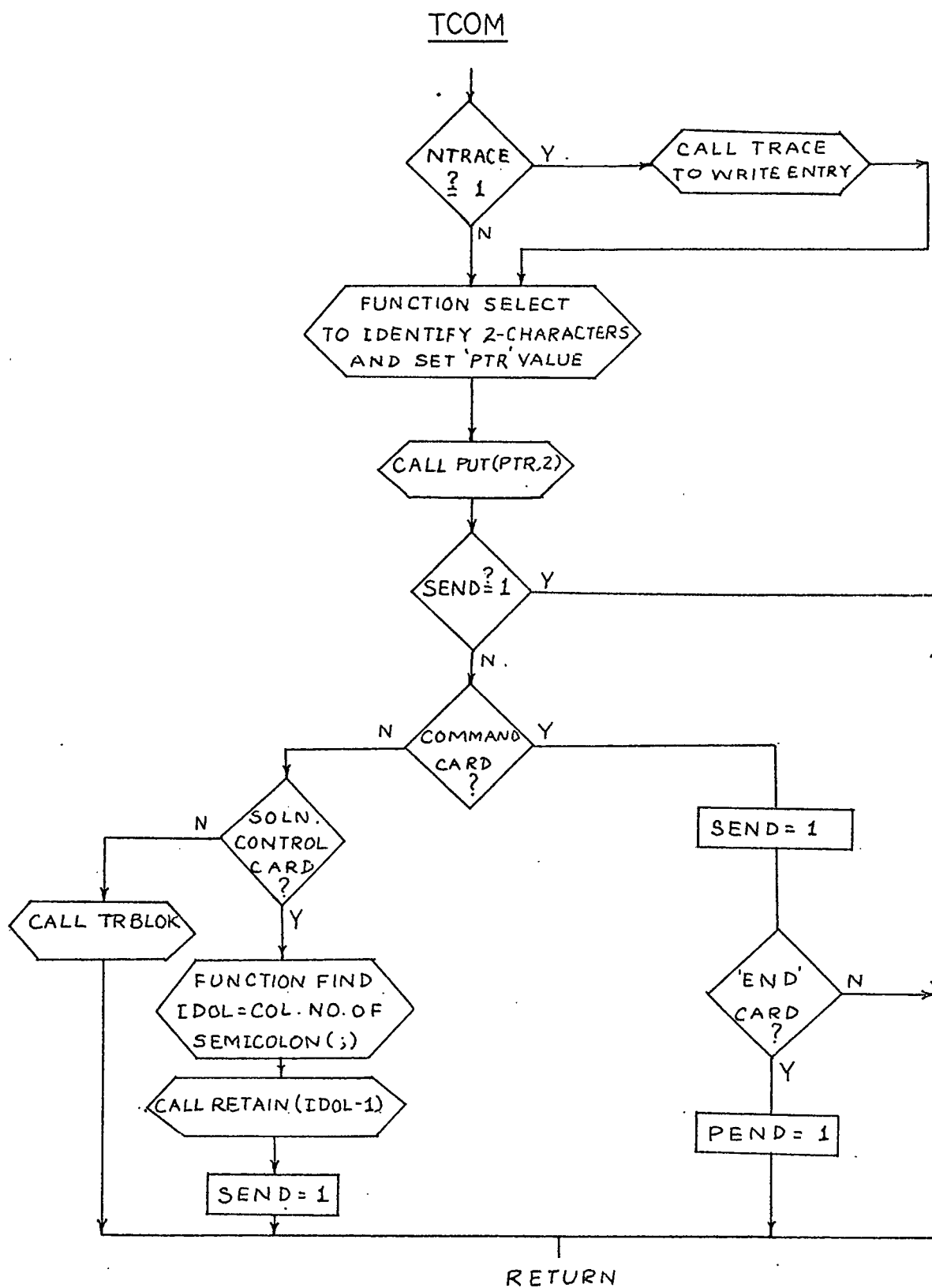
As an aid in following the processor listings and flowcharts, a brief summary of routines is given.

MAIN	Primary routine of ECAP which calls ULANG
ULANG	Controlling routine of the processor
SYSID	System identifier routine
READER	Card image reader
DUMP	Routine to write the card image
BLANK	Routine to check if the first six columns of a card image are blanks
LETTER	Function to check an alphabetic character
FIND	Function to determine the column number of a particular character
LOCATE	Routine to compare and recognize single character identifier
SELECT	Routine to compare and recognize two character identifier
PUT	Routine to substitute appropriate character from symbol tables
TCOM	Controlling routine for command type, solution control type and output specification type cards

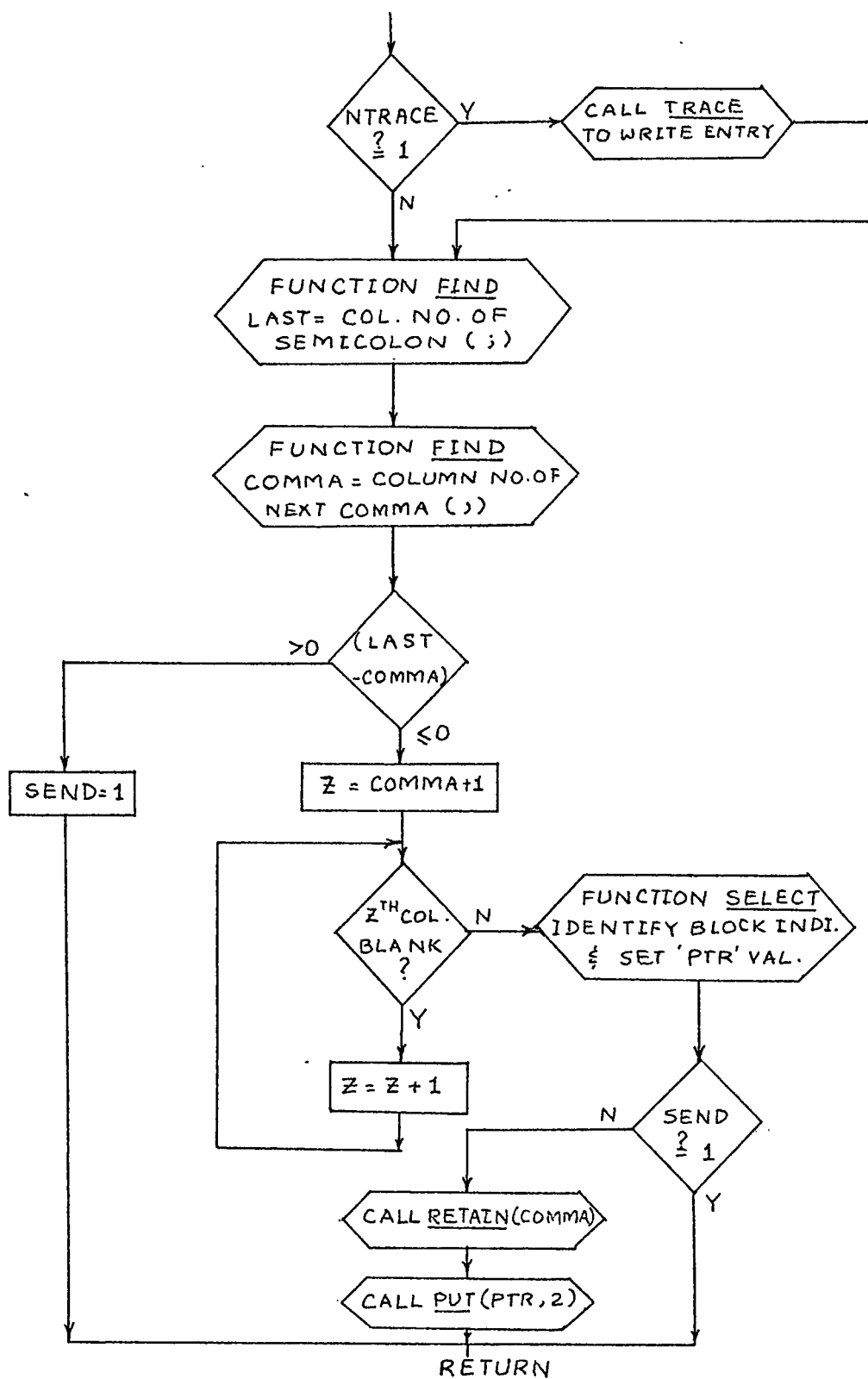
TRBLOK	Routine for translating output block indicators
TSOL	Character manipulator routine for data type cards
SOLN	Data type card recognizer routine
DIAG	Routine to print out diagnostic message
TRACE	Tracing routine
RETAIN	Routine to copy a string of characters
PLACE	Routine to replace a string of characters
INIT	Routine to initialize work arrays

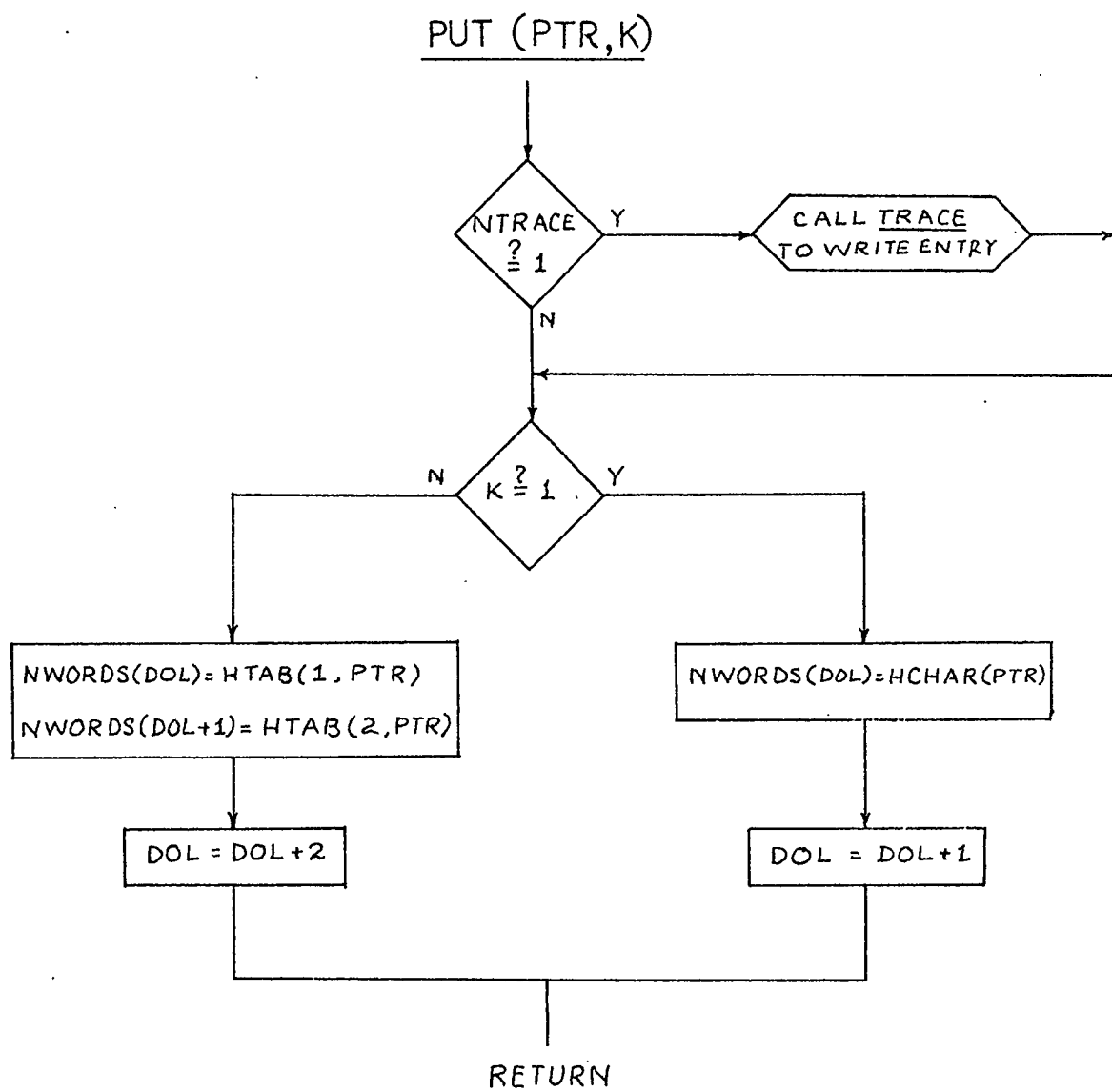


ULANG ... CONTD.

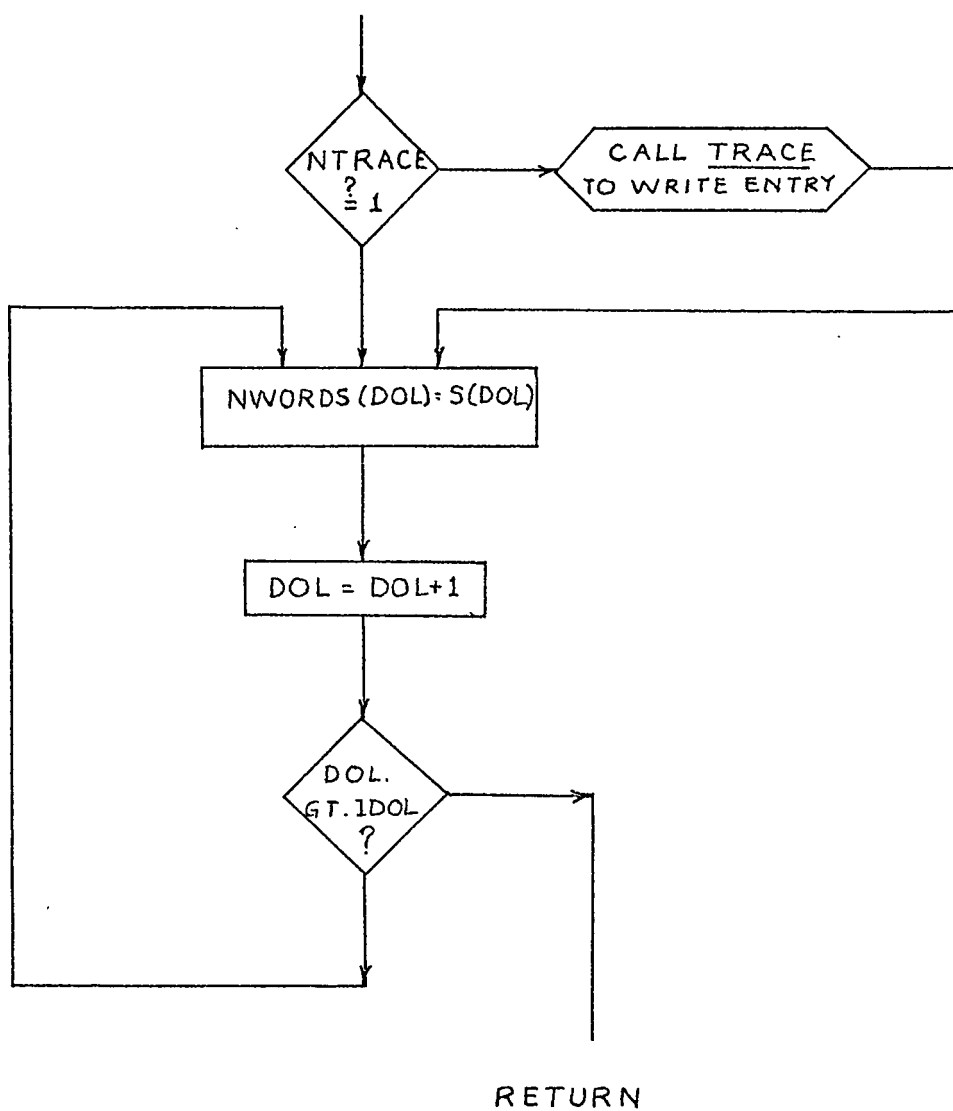


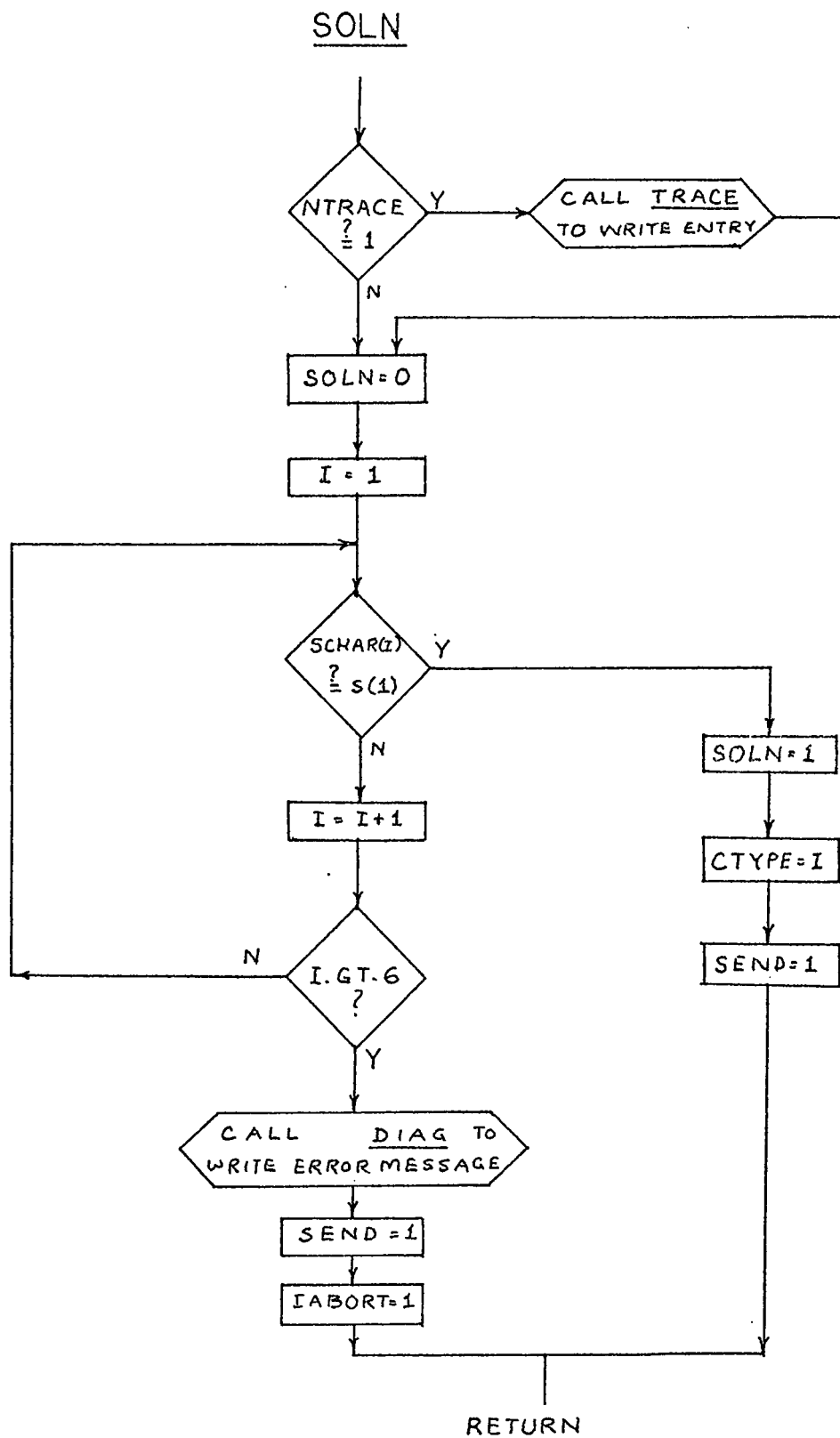
TRBLOK

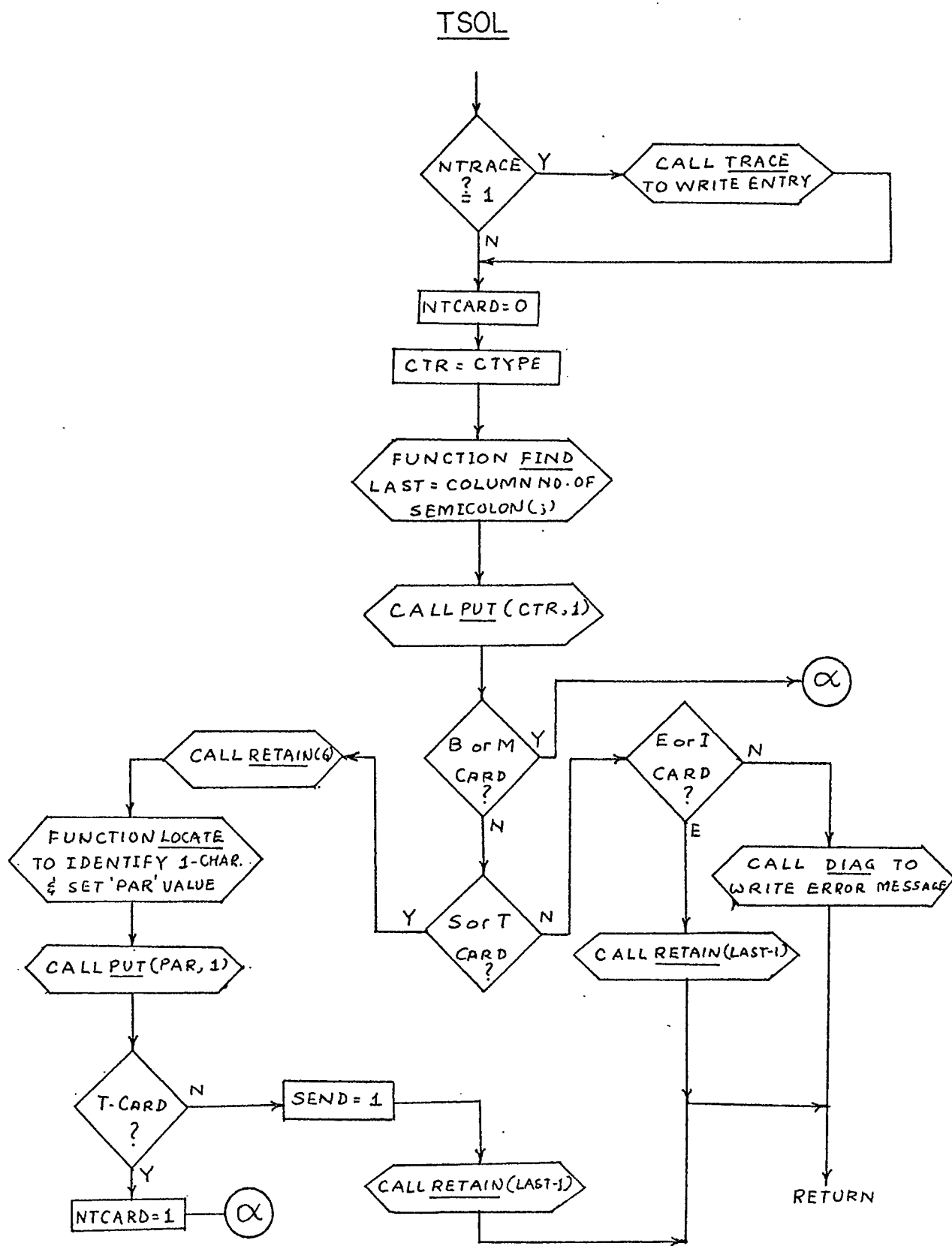




RETAIN (IDOL)

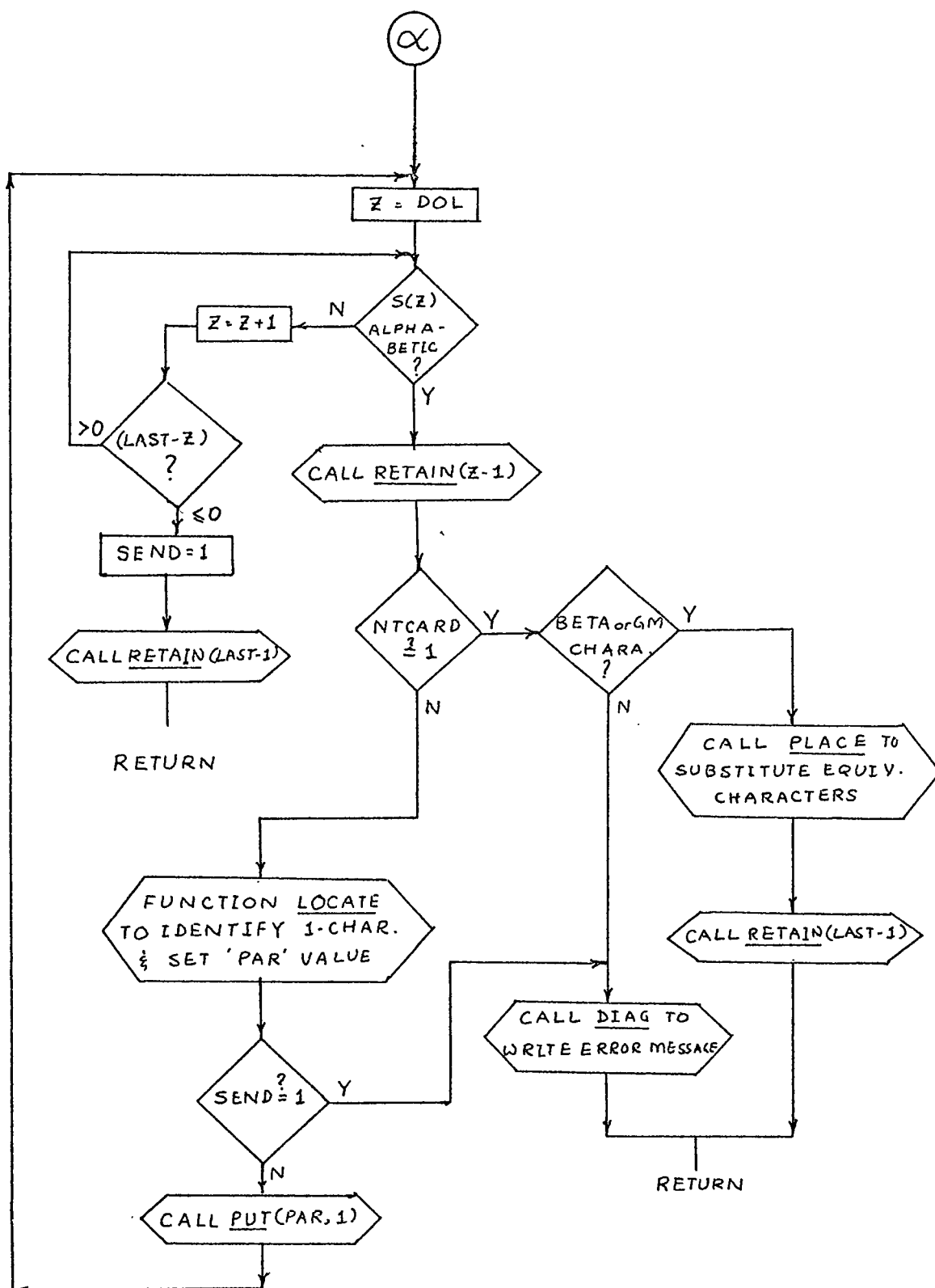






CONTD. ON NEXT PAGE

TSOL ... CONTD.



APPENDIX B

UHSAP LANGUAGE SPECIFICATIONS

TABLE 1
DATA CARD TYPES AND SPECIFICATIONS

Card contents	Electrical	Mech. Transl.	Mech. Rota.	Acoustical	Thermal
Branch (Path) Data	<i>Bnn</i>	<i>Pnn</i>	<i>Pnn</i>	<i>Bnn</i>	<i>Bnn</i>
Dep. Source Data	<i>Tnn</i>	<i>Dnn</i>	<i>Dnn</i>	<i>Dnn</i>	<i>Tnn</i>
Sensing E . Data	<i>Snn</i>	<i>Snn</i>	<i>Snn</i>	<i>Snn</i>	<i>Snn</i>
Mutual Inductance Data	<i>Mnn</i>	-	-	-	-

TABLE 2

ALLOWABLE ELEMENT IDENTIFIERS FOR B-CARDS

ELECTRICAL (Electrical Code)	MECHANICAL (Mechanical Code)	ROTATIONAL (Rotational Code)	THERMAL (Thermal Code)	ACOUSTICAL (Acoustical Code)
Resis- tance R	-	-	Thermal Resis- tance R	Acoustic Resis- tance R
Capaci- tance C	Mass M	Polar Mmt. of Inertia J	Thermal Capaci- tance C	Acoustic Capaci- tance C
Induc- tance L	Spring K	Torsional Spring K	-	Iner- tance M
Conduc- tance G	Dashpot B	Damping Factor B	Thermal Conduc- tivity K	-
Voltage Source E	Velocity Source V	Angular Vel. W	Tempera- ture Dif- ference T	Pressure Differ- ence P
Current Source I	Force F	Torque T	Heat Source Q	Volume Vel. U

TABLE 3*

SOLUTION CONTROL CARDS

Solution Control Card	Description of variable q
<i>FREQUENCY = q</i>	Frequency for AC type sources.
<i>TIME STEP = q</i>	Transient analysis time step Δt .
<i>OUTPUT = q</i>	Number of time steps per output interval.
<i>FINAL TI = q</i>	Final Time for transient solution.
<i>SENSITIVITY</i>	Requests sensitivity and partial derivative calculations.
<i>WORST CASE</i>	Requests worst case as well as sensitivity calculations.
<i>STANDARD DEV.</i>	Requests worst case and sensitivity.
<i>EQUILIBRIUM</i>	Indication of steady state solution desired.

*Adapted from Reference No. 3, page 32.

TABLE 4

VALID OUTPUT BLOCK INDICATORS

ELECTRICAL		MECHANICAL		ROTATIONAL		THERMAL		ACOUSTICAL	
Description of output	Indi- cator code	Description of output	Indi- cator code	Description of output	Indi- cator code	Description of output	Indi- cator code	Description of output	Indi- cator code
Node Volt- age	NV or VØ	Node Ve- locities	VE	Node Ang. Velocity	AN	Node Temp.	TE	Node Pres. Diff.	PR
El. Cur- rents	CU or CA	Forces in Element	FØ	Torque in Element	TØ	Heat in Elements	HE	Vol. Veloc- ity in El.	VØ
El. vol- tage	CV	Vel. in Element	EV	Ang. Vel. in Element	WE	Tem. diff. in Element	ET	Pressure diff. in Element	PE
Br. Curr.	BA	Forces in Branches	PF	Branch Torque	PT	Branch Heat	BQ	Branch Vol. Vel.	BU
Br. Voltage	BV	Velo. of Branch El.	PV	Branch Ang. Vel.	PW	Branch Temp. diff.	BT	Branch Pres. diff.	BP
Element Power loss	BP	Power loss in Branch	PP	Power loss in Branch	BP	Power loss in Branch	BP	Power loss in Branch	PP
Sensitivity	SE		SE		SE		SE		SE
Worst Case	WØ		WØ		WØ		WØ		WØ
Standard Dev.	ST		ST		ST		ST		ST

TABLE 5

DESCRIPTION OF COMMAND CARDS

I. ANALYSIS COMMANDS

Electrical Analysis Code		Mechanical Analysis Code		Rotational Analysis Code		Acoustical Analysis Code		Thermal Analysis Code	
DC Analy.	DC	Unidirect. Source Analysis	UD	Constant Ang. Vel. Analysis	UD	Constant Vol. Vel. Analysis	CU	Constant Heat Flow Analysis	CH
AC Analy.	AC	Alternating Force Analysis	AF	Alternating Torque Analysis	AT	Alternating Vol. Vel. Analysis	AU	Alternating Heat Flow Analysis	AH
Transient Analysis	TR	Dynamic Analysis	DY	Dynamic Analysis	DY	Transient Analysis	TR	Transient Analysis	TR

II. EXECUTIVE COMMANDS

FUNCTIONCOMMAND CODE IN ALL 5 SYSTEMS

Modification calls
for repeat calcula-
tions with modified
data

MØ

End of input data
for problem, request
for solution

EX

End of job

EN

APPENDIX C

I. Language Processor Routine Listings

49

```

C
C   CONTROLLING ROUTINE ULANG FOR
C   THE UNSAP LANGUAGE PROCESSOR
C
C   SUBROUTINE ULANG
C   IMPLICIT INTEGER (A-Z)
C   COMMON/INTER/NTRACE,DOL,S(80),SEND,PEND
C   COMMON/SYMBOL/ALPH(26),NUM(10)
C   COMMON/OUT/WORDS(30)
C   COMMON/MYS/EYSYS
C   COMMON/ABO/IABORT
C   DIMENSION STAR(6)
C   DATA STAR,BL /' ','T','R','A','C','E',' '/
C   NTRACE=0
C   WRITE(6,201)
201  FORMAT(1H1)
C   CALL SYSID
C   IF(MYSYS-1) 150,160,170
170  IABORT=0
10   CALL READER
C   DO 180 I=1,6
C   IF(S(I)-STAR(I)) 190,180,190
180  CONTINUE
C   NTRACE=1
C   CALL DUMP(S)
C   GO TO 80
190  CONT=0
C   IF(S(1)-ALPH(3)) 20,30,20
30   CALL DUMP(S)
C   GOTO10
20   CALL DUMP(S)
C   IF(BLANK(BL )) 40,40,50
50   CALL TCOM
C   GOTO 80
40   IF(S(6)-BL ) 90,60,90
60   IF(SOLN(DOL))110,110,120
120  CALL TSOL
C   GOTO80
90   IF(CONT,EQ,1) GOTO 80
C   CONT=1
C   GOTO 50
110  CALL DIAG('IMPROPER SPECIFICATION
RETURN
80   WRITE(1)(WORDS(I),I=1,72)
C   IF(PEND)10,10,130
130  CONTINUE

```

```

      IF(IABORT, EQ, 0) GOTO200
150  WRITE(6, 1111)
1111  FORMAT(10X, '**** JOB NOT RUN BECAUSE OF FATAL ERRORS ****')
      IABORT=1
160  RETURN
200  CONTINUE
      END FILE 1
      REWIND 1
      RETURN
      END

```

C
C
C
C
C
C

INTEGER FUNCTION ICHK TO CHECK A PARTICULAR
STRING OF CHARACTERS TO MATCH WITH VECTOR V

```

      INTEGER FUNCTION ICHK(V, N)
      IMPLICIT INTEGER (A-Z)
      COMMON/INTER/NTRACE, DOL, S(30), SEND, PEND
      COMMON/BETAGM/BETA(4), GM(2), HBETA(4), HGM(2)
      COMMON/ABO/IABORT
      DIMENSION V(10)
      IF(NTRACE)101,102,101
101  CALL TRACE('FUNCTION ICHK', 1)
102  ICHK=0
      DO 20 I=1, N
      IF(S(DOL+I-1)-V(I)) 10,20,10
20  CONTINUE
      ICHK=1
      RETURN
10  IF(N, EQ, 2) IABORT=1
      RETURN
      END

```

C
C
C
C
C

PLACE ROUTINE TO PUT CHARACTERS IN THE VECTOR V .

```

      SUBROUTINE PLACE(V, N)
      IMPLICIT INTEGER (A-Z)
      DIMENSION V(10)
      COMMON/INTER/NTRACE, DOL, S(30), SEND, PEND
      COMMON/BETAGM/BETA(4), GM(2), HBETA(4), HGM(2)
      COMMON/OUT/NWORDS(30)
      IF(NTRACE)101,102,101
101  CALL TRACE('SUBROUTINE PLACE', 1)
102  DO 10 I=1, N
10  NWORDS(DOL+I-1)=V(I)
      DOL=DOL+N
      RETURN
      END

```



```

C
C
C      SUBROUTINE TO INITIALIZE WORK ARRAYS
C      ACCORDING TO THE SYSTEM SPECIFICATION
C
C      SUBROUTINE INIT(VNAME)
C      IMPLICIT INTEGER (A-Z)
C      COMMON/SYSTEM/MECH(2,70),ROTA(2,70), THER(2,70),ACOU(2,70)
C      COMMON/TABLES/STAB(2,50),HTAB(2,50),SCHAR(40),HCHAR(40)
C      DO 20 I=1,2
C      DO 10 J=1,50
10      STAB(I,J)=VNAME(I,J)
C      DO 20 J=51,70
20      SCHAR(I+J-50)=VNAME(I,J)
C      RETURN
C      END
C
C
C      SUBROUTINE TO IDENTIFY THE SYSTEM
C      SPECIFICATION AND SET MYSYS VALUE
C
C
C      SUBROUTINE SYSID
C      IMPLICIT INTEGER (A-Z)
C      COMMON/SYSTEM/MECH(2,70),ROTA(2,70), THER(2,70),ACOU(2,70)
C      COMMON/INTER/INTERFACE,DOL,S(32)
C      COMMON/MYS/YSIS
C      DIMENSION SYS(2,6)
C      DATA SYS /'E','L','H','E','R','O','T','H','A','C',2*0/
C      CALL READER
C      CALL DUMP(S)
C      DO 30 P=1,6
C      IF( S (1)-SYS(1,P)) 70,10,30
10      IF( S (2)-SYS(2,P))30,40,30
30      CONTINUE
C      MYSIS=0
C      CALL DIAG('INVALID SYSTEM IDENTIFIER CARD')
C      RETURN
40      MYSIS=P
C      GO TO (100,200,300,400,500),MYSIS
100      RETURN
200      CALL INIT (MECH)
C      RETURN
300      CALL INIT (ROTA)
C      RETURN
400      CALL INIT (THER)
C      RETURN
500      CALL INIT(ACOU)
C      RETURN
C      END

```

C
C
C
C
C
C

SUBROUTINE TCOM TO DETERMINE VALID
110-CHARACTER IDENTIFIERS

```

SUBROUTINE TCOM
  IMPLICIT INTEGER (A-Z)
  COMMON/INTER/NTRACE,DOL,S(30),SEND,PEND
  DATA IHYPH/' ','/'
  IF(NTRACE)101,102,101
101 CALL TRACE('SUBROUTINE TCOM
102 PTR=SELECT(DOL,1,19)
  IF (SEND)40,40,100
40 CALL PUT(PTR,2)
  IF (PTR-10)50,50,70
50 SEND=1
  IF (PTR,EO.6) PEND=1
  RETURN
70 IF (PTR-16) 80,80,90
80 IDOL=FINO(IHYPH)
  IDOL=IDOL-1
  CALL RETAIN(IDOL)
  SEND=1
  RETURN
90 CALL TRBLOK
100 RETURN
END

```

C
C
C
C
C
C

SUBROUTINE TRBLOK TO RECOGNIZE AND
REPLACE OUTPUT BLOCK INDICATORS

```

SUBROUTINE TRBLOK
  IMPLICIT INTEGER (A-Z)
  COMMON/INTER/NTRACE,DOL,S(30),SEND,PEND
  DATA BL/' ','/'
  DATA IHYPH/' ','/' ,ICOMMA/' ','/'
  IF(NTRACE) 101,102,101
101 CALL TRACE('SUBROUTINE TRBLOK
102 LAST=FINO(IHYPH)
80 COMMA=FINO(ICOMMA)
  IF (LAST-COMMA) 100,100,10
10 Z=COMMA+1
  IF (S(Z)-BL) 30,20,30
20 Z=Z+1
  GO TO 10

```

```

30   PTR=SELECT(Z,20,31)
    IF(SEND) 60,60,70
70   RETURN
60   CALL RETAIN(COMMA)
    CALL PUT(PTR,2)
    GO TO 80
100  SEND=1
    RETURN
    END

C
C
C   FUNCTION SOLN TO DETERMINE IF THE CARD
C   IS OF SOLUTION CONTROL TYPE
C
C
C   FUNCTION SOLN(KDOL)
C   NOTE THAT KDOL IS A DUMMY VARIABLE
    IMPLICIT INTEGER (A-Z)
    COMMON /TABLES/STAG(50,2),HTAB(50,2),SCHAR(40),HCHAR(40)
    COMMON/INTER/NTRACE,DOL,S(80),SEND,PEND
    COMMON CTYPE
    COMMON/ABO/IABORT
    IF(NTRACE)101,102,101
101  CALL TRACE('FUNCTION SOLN'           ')
102  SOLN=0
    DO 10 I=1,6
    IF(S(1)-SCHAR(I))10,20,10
10  CONTINUE
    SEND=1
    CALL DIAG('ILLEGAL CHARACTER IN FIRST COLUMN' ')
    IABORT=1
    RETURN
20  SOLN=1
    CTYPE=1
    RETURN
    END

C
C
C   INTEGER FUNCTION BLANK TO DETERMINE IF
C   THE FIRST SIX COLUMNS ARE BLANKS
C
C
C   INTEGER FUNCTION BLANK(KDOL)
    IMPLICIT INTEGER (A-Z)
    COMMON/INTER/NTRACE,DOL,S(80),SEND,PEND
    COMMON/OUT/WORKS(50)
    DATA BL/' ' /
    IF(NTRACE)101,102,101
101  CALL TRACE('FUNCTION BLANK'         ')

```

```

102  BLANK=1
      DO 10 AUX=1,6
      IF (S(AUX)-1L) 20,10,20
10    NWORDS(AUX)=S(AUX)
      DOL=7
      RETURN
20    BLANK=0
      RETURN
      END

C
C
C    SUBROUTINE DUMP TO WRITE THE ARRAY
C
C

      SUBROUTINE DUMP(V)
      IMPLICIT INTEGER(A-Z)
      DIMENSION V(80)
      COMMON /INTER/NTRACE,RN(83)
      IF(NTRACE)101,102,101
101   CALL TRACE('SUBROUTINE DUMP'           ')
102   WRITE(6,100) (V(I),I=1,72)
100   FORMAT(5X,72A1)
      RETURN
      END

C
C
C    FUNCTION LETTER TO CHECK IF THE CHARACTER
C    IN COLUMN X IS AN ALPHABETIC CHARACTER
C
C

      INTEGER FUNCTION LETTER(X)
      IMPLICIT INTEGER (A-Z)
      COMMON/SYMBOL/ALPH(26),NUM(10)
      COMMON/INTER/NTRACE,DOL,S(80),SEND,PEND
      IF(NTRACE)101,102,101
101   CALL TRACE('FUNCTION LETTER           ')
102   IF(S(X)-ALPH(1))3,2,1
1    IF(S(X)-ALPH(26))2,2,3
2    LETTER=1
      RETURN
3    LETTER=0
      RETURN
      END

```

```

C
C
C      SUBROUTINE PUT TO REPLACE A STRING OF CHARACTERS
C
C
      SUBROUTINE PUT (PTR,K)
      IMPLICIT INTEGER (A-Z)
      COMMON/TABLES/STAB(2,50),HTAB(2,50),SCHAR(40),HCHAR(40)
      COMMON/INTER/NTRACE,DOL,S(80),SEND,PEND
      COMMON/OUT/NWORDS(60)
      IF(NTRACE)101,102,101
101  CALL TRACE('SUBROUTINE PUT              ')
102  GO TO (20,10),K
10   NWORDS(DOL)=HTAB(1,PTR)
      NWORDS(DOL+1)=HTAB(2,PTR)
      DOL=DOL+2
      RETURN
20   NWORDS(DOL)=HCHAR(PTR)
      DOL=DOL+1
      RETURN
      END

C
C
C      SUBROUTINE READER TO READ A NEW CARD
C      ALSO TO SET POINTER ON ONE AND SEND=0
C
C
      SUBROUTINE READER
      IMPLICIT INTEGER (A-Z)
      COMMON/INTER/NTRACE,DOL,S(30),SEND,PEND
      COMMON/OUT/NWORDS(80)
      DATA RL/' '/
      IF(NTRACE)101,102,101
101  CALL TRACE('SUBROUTINE READER          ')
102  SEND=0
      PEND=0
      DOL=1
      READ(5,100)(S(I),I=1,72)
100  FORMAT(72A1)
      DO 200 J=9,30
200  NWORDS(J)=RL
      RETURN
      END

```

```

C
C
C      INTEGER FUNCTION TO SELECT PARTICULAR TYPE
C      OF CHARACTERS IN THE INPUT STRING
C
      INTEGER FUNCTION SELECT(Z,INIT,FIN)
      IMPLICIT INTEGER (A-Z)
      COMMON/TABLES/STAB(2,50),HTAB(2,50),SCHAR(40),HCHAR(40)
      COMMON/INTER/NTRACE,DOL,S(80),SEND,FEND
      COMMON/ABORT/IABORT
      IF(NTRACE)101,102,101
101  CALL TRACE('FUNCTION SELECT          ')
102  DO 30 VAL=INIT,FIN
      IF(S(Z)-STAB(1,VAL))30,40,30
40   IF(S(Z+1)-STAB(2,VAL))30,50,30
30   CONTINUE
      CALL DIAG('INVALID TWO CHARACTER IDENTIFIER IN THE CARD ')
      SEND=1
      IABORT=1
      SELECT=0
      RETURN
50   SELECT=VAL
      RETURN
      END

C      INTEGER FUNCTION TO DETERMINE A PARTICULAR CHARACTER
C      IN THE STRING AND GET THE CORRESPONDING COLUMN NUMBER
C
      INTEGER FUNCTION FIND(V)
      IMPLICIT INTEGER (A-Z)
      COMMON/INTER/NTRACE,DOL,S(80),SEND,FEND
      DATA ISEMI/' ';'
101  CALL TRACE('FUNCTION FIND          ')
102  DO 20 AUX=DOL,80
      IF(S(AUX)-V) 20,10,20
20   CONTINUE
      IF(V,NE,ISEMI) GOTO30
      CALL DIAG('STATEMENT DELIMITER MISSING -ASSUMED AT 72  ')
30   FIND=72
      RETURN
10   FIND=AUX
      RETURN
      END

```

```

C
C
C      SUBROUTINE RETAIN TO COPY A STRING OF CHARACTERS AS THEY ARE
C
C      SUBROUTINE RETAIN(IDOL)
C      IMPLICIT INTEGER (A-Z)
C      COMMON/OUT/NWORDS(80)
C      COMMON/INTER/NTRACE,DOL,S(80),SEND,PEND
C      IF(NTRACE)101,102,101
101  CALL TRACE('SUBROUTINE RETAIN          ')
102  DO 10 P=DOL,IDOL
10   NWORDS(P)=S(P)
C      DOL=IDOL+1
C      RETURN
C      END

C
C
C      SUBROUTINE TRACE TO DETERMINE THE FLOW OF CONTROL
C
C      SUBROUTINE TRACE(V)
C      IMPLICIT INTEGER (A-Z)
C      DIMENSION V(10)
C      WRITE(6,1)(V(I),I=1,7)
1   FORMAT(3X,'ENTRY : ',5X,7A4)
C      RETURN
C      END

C
C
C      ERROR SUBROUTINE TO WRITE THE ERROR MESSAGE
C
C      SUBROUTINE DIAG(V)
C      IMPLICIT INTEGER (A-Z)
C      DIMENSION V(20)
C      COMMON/INTER/NTRACE,REM(63)
C      IF(NTRACE)101,102,101
101  CALL TRACE('SUBROUTINE DIAG          ')
102  WRITE(6,1)(V(I),I=1,17)
1   FORMAT(//,10X,'***DIAGNOSTIC : ',17A4,//)
C      RETURN
C      END

```

C
C
C
C
C
C

SUBROUTINE TSOL FOR RECOGNIZING AND
MANIPULATING CHARACTERS IN CASE OF DATA CARDS

```

SUBROUTINE TSOL
IMPLICIT INTEGER (A-Z)
COMMON/TABLES/STAB(50,2),HTAB(50,2),SCHAR(40),PCHAR(40)
COMMON/INTER/NTRACE,DOL,S(80),SEND,PEND
COMMON CTYPE
COMMON/BETAGM/BETA(4),GM(2),HBETA(4),HGM(2)
DATA IHYPH/' ';'/
IF(NTRACE)101,102,101
101 CALL TRACE('SUBROUTINE TSOL' )
102 NTCARD=0
CTR=CTYPE
LAST=FIND(IHYPH)
IF(SEND)10,10,20
20 CALL DIAG('INVALID CARD SPECIFICATION' )
RETURN
10 CALL PUT(CTR,1)
GO TO (30,40,40,30,70,70),CTR
70 IDOL=LAST-1
CALL RETAIN(IDOL)
RETURN
30 Z=DOL
80 IF(LETTER(Z)) 50,50,60
50 Z=Z+1
IF(LAST-Z) 120,120,30
60 AUX=Z-1
CALL RETAIN(AUX)
IF (NTCARD) 230,230,240
230 PAR=LOCATE(DOL,5,13)
IF(SEND)90,90,100
100 CALL DIAG('INVALID PARAMETER SPECIFICATION' )
RETURN
90 CALL PUT(PAR,1)
GOTO30
120 SLEN=1
AUX=LAST-1
CALL RETAIN(AUX)
RETURN
40 CALL RETAIN(6)
PAR=LOCATE (7,11,12)
CALL PUT(PAR,1)
IF(CTR,EQ,3) GO TO 140
130 VAL=LAST-1

```



```

      CALL RETAIN(VAL)
      SEND=1
      RETURN
140   NTCARD=1
      GOTO30
240   IF(ICHK(BETA,4))250,250,260
250   IF (ICHK(GM,2))270,270,290
270   CALL DIAG('INVALID CHARACTERS IN DEPENDENT SOURCE CARD
      RETURN
260   CALL PLACE(HBETA,4)
      GOTO280
290   CALL PLACE(HGM,2)
280   IDOL=LAST-1
      CALL RETAIN(IDOL)
      RETURN
      END

C
C
C   FUNCTION TO LOCATE A PARTICULAR CHARACTER AND TO ASSIGN
C   THE VALUE OF THE MATCHING CHARACTER FROM THE TABLE
C
C
      INTEGER FUNCTION LOCATE(Z,F,L)
      IMPLICIT INTEGER (A-Z)
      COMMON /TABLES/STAB(50,2),HTAB(50,2),SCHAR(40),PCHAR(40)
      COMMON/INTER/NTRACE,DOL,S(80),SEND,FEND
      COMMON/ABO/IABORT
      IF(NTRACE)101,102,101
101   CALL TRACE('FUNCTION LOCATE
102   LOCATE=0
      DO20PTR=F,L
      IF(S(Z)-SCHAR(PTR))20,10,20
20   CONTINUE
      SEND=1
      CALL DIAG('ILLEGAL CHARACTER IN INPUT
      IABORT=1
      RETURN
10   LOCATE=PTR
      RETURN
      END

```

II. Listing Showing Modifications Needed in ECAP Routines

For implementation of UHSAP at other installations, a few cards may have to be removed from and a few added to the ECAP routines. The cards to be added have been shown in appropriate places with identification sequence numbers. A line has been drawn on the identification sequence numbers in case of cards that need to be removed from ECAP routines.

The following pages contain the listings for the purposes of implementation.

```

C
C * * * * *
C
C DIMENSION LIST4(200),LABEL(200),LISTE(5),LISTI(5),NUME(5),NUMI(5) ECAP0000
C DIMENSION LINK10(200),LINK1E(200) ECAP0010
C ECAP0020
C COMMON/TABLES/IDUN(280) ADEC0010
C COMMON/INTER/IDUM(84) ADEC0020
C COMMON/OUT/AW(80) ADEC0030
C COMMON/SYMBOL/IONE(36) ADEC0040
C COMMON/MYS/MYSYS ADEC0050
C COMMON/ABO/IABOFT ADEC0060
C COMMON NMAX,NMODE,INTERMS,NUNBL,NUMBR,NUMBC,IRTN,NTRACE,NSWICH,KTO, ECAP0030
1 NPRINT(10) ECAP0040
C COMMON E(200),EMIN(200),EMAX(200),AMP(200),AMPMIN(200),AMPMAX(200) ECAP0050
C COMMON Y(200),YMIN(200),YMAX(200),NINIT(200),NFIN(200),MODE1(200) ECAP0060
C COMMON YTERM(200),YTERMH(200),YTERML(200),IPOWER(200),ICOLT(200) ECAP0070
C COMMON ERROR1,ISEQ,MSEQ,M0,ROMM0,VFIRST(50),VSECND(50),VLAST(50) ECAP0080
C COMMON MUBRN(50),MOPAP1(50),MOSTEF(50),IWCOU(4),NLTRMS,DELTA ECAP0090
C COMMON IROWN(50),ICOLN(50),FLML(50),FLMH(50),FLH(50),EPHA(200), ECAP0100
1 APPPHA(200),MFLC,MAJOR,ERRCR2,ERRCR3,ETIME(5,2),ATIME(5,2) ECAP0110
C COMMON ETR(5,126),AMPTR(5,126) ECAP0120
C ECAP0130
C THE FOLLOWING VARIABLES ARE USED ONLY IN THE ECAP LANGUAGE PROG. ECAP0140
C ECAP0150
C COMMON NWORDS(72),NMCD(2,20),KLABEL(4),KPUNC(5),INDC(2,20) ECAP0160
C COMMON INPUTR(9),NRCU(20),KTYPE(5),NCLANK,POEXEC,ITOL,NFOUIN,IPC ECAP0170
C COMMON INVAL,LL,ICOL,LTYPE,KCOL,NOUIT,ITRANS,KC,KC,KELAST,NUM,M1 ECAP0180
C COMMON M2,M3,KCARD,K6,MP,NTR,MAG,HNODE,TNUM,NOEL,NOE,NOI,NOIC ECAP0190
C COMMON EQUIVN(20),KOUT(2,10) ECAP0200
C ECAP0210

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	EQUIVALENCE (YTERM(1),LIST4(1)),(ISEQ,START),(MSEQ,FINISH),	ECAP0220
	1 (NUMNO,SHORT),(VFIRST(2),LABEL(1)),(IWCOUT(2),KE),(IWCOUT(3),KI),	ECAP0230
	2 (IWCOUT(4),NOSW),(DELTA,OMEGA),(FLM(1),LISTE(1)),	ECAP0240
	3 (FLM(6),LISTI(1)),(FLM(11),NUME(1)),(FLM(16),NUMI(1)),	ECAP0250
	4 (EPHA(1),LINK1D(1)),(AMPPHA(1),LINK1E(1)),(VFIRST(1),OPEN)	ECAP0260
C		ECAP0270
C		ECAP0280
	NTRACE=0	ECAP0290
	KTO = 1	ECAP0300
	CALL ULANG	ADEC0070
	IF(IABORT,EQ,1) STOP	ADEC0080
1	CALL ECA	ECAP0310
	GO TO(2,3,4),NTR	ECAP0320
2	CALL ECA19	ECAP0330
	GO TO 5	ECAP0340
3	CALL ECA39	ECAP0350
	GO TO 5	ECAP0360
4	CALL ECA69	ECAP0370
5	KTO = 2	ECAP0380
	GO TO 1	ECAP0390
	END	ECAP0400
	SUBROUTINE ECA	LA000000
C		LA000010
C	CARD IMAGE LOADER FOR ELECTRICAL NETWORK ANALYSIS.	LA000020
C		LA000030
C		LA000040
	DIMENSION LIST4(200),LABEL(200),LISTE(5),LISTI(5),NUME(5),NUMI(5)	LA000050
	DIMENSION LINK1D(200),LINK1E(200)	LA000060
	COMMON/MYS/MYSYS	AD000010
C		LA000070
	COMMON NMAX,NNODE,NTURNS,NUMBL,NUMER,NUMBC,IRTY,NTRACE,NSWTH,KTO,	LA000080
1	NPRINT(10)	LA000090
	COMMON E(200),EMIN(200),EMAX(200),AMP(200),AMPMIN(200),AMPMAX(200)	LA000100
	COMMON Y(200),YMIN(200),YMAX(200),PINIT(200),NFIN(200),MODE1(200)	LA000110

	COMMON YTERM(200),YTERMH(200),YTERML(200),IROWT(200),ICOLT(200)	LA000120
	COMMON ERROR1,ISEQ,MSEQ,MO,NUMMO,VFIRST(50),VSECND(50),VLAST(50)	LA000130
	COMMON MOPRM(50),MOPARM(50),MNSTEP(50),IWCOUT(4),NLTRMS,DELTA	LA000140
	COMMON IROWM(50),ICOLM(50),FLML(50),FLPH(50),FLM(50),EPHA(200),	LA000150
	1 AMPPHA(200),MREC,YAJOR,ERROR2,ERROR3,ETIME(5,2),ATIME(5,2)	LA000160
	COMMON ETR(5,126),AMPTR(5,126)	LA000170
C		LA000180
C	THE FOLLOWING VARIABLES ARE USED ONLY IN THE ECAP LANGUAGE PROG.	LA000190
C		LA000200
	COMMON NWORDS(72),MHCD(2,20),KLABEL(4),KPUNC(5),INDC(2,20)	LA000210
	COMMON INPUTR(5),NBCD(20),KTYPE(5),NBLANK,NOEXEC,ITOL,NEQUIM,IPC	LA000220
	COMMON INVAL,LL,ICOL,LTYPE,KCOL,NQUIT,ITRANS,KO,KS,KELAST,NUM,N1	LA000230
	COMMON M2,M3,KCARD,KG,NP,NTR,HAC,HNODE,TNUM,NOEL,NOE,NOI,NOIC	LA000240
	COMMON EQUIVN(20),KOUT(2,10)	LA000250
C		LA000260
	EQUIVALENCE (YTERM(1),LIST4(1)),(ISEQ,START),(MSEQ,FINISH),	LA000270
	1 (NUMMO,SHORT),(VFIRST(2),LABEL(1)),(IWCOUT(2),KE),(IWCOUT(3),KI),	LA000280
	2 (IWCOUT(4),NOSW),(DELTA,OMEGA),(FLM(1),LISTE(1)),	LA000290
	3 (FLM(6),LISTI(1)),(FLN(11),NUME(1)),(FLM(16),NUMI(1)),	LA000300
	4 (EPHA(1),LINKID(1)),(AMPPHA(1),LINKIE(1)),(VFIRST(1),OPEN)	LA000310
C		LA000320
C		LA000330
C		LA000340
	IF (NTRACE) 3, 4, 3	LA000350
2	FORMAT(' LANG MAINLINE- ECA ENTERED. KTD = ',I3)	LA000360
3	WRITE (6, 2) KTD	LA000370
4	GO TO (1,44),KTD	LA000380
1	CALL ECA01	LA000390
	WRITE (6, 702)	LA000400
702	FORMAT (1H1)	LA000410
100	READ(5,700) (NWORDS(J),J=1,72)	LA000420
100	IF(MYSYS.EQ.1) GOTO10	AD000020
	READ(1) (NWO RDS(J),J=1,72)	AD000030
	GOTO20	AD000040
10	READ(5,700) (NWORDS(J),J=1,72)	AD000050

20	IF (NWORDS(1) - NBCD(1)) 99, 1000, 99	LA0000430
99	IF(MYSYS.NE.1) GO TO 92	A00000060
	WRITE(6,701) (NWORDS(J),J=1,72)	A00000070
99	WRITE(6,701) (NWORDS(J),J=1,72)	LA0000440
92	N0EXEC = N0EXEC + NQUIT	LA0000450
	KCARD = KCARD + 1	LA0000460
	IF (NWORDS(1) - NMCD(2, 1)) 7777, 100, 7777	LA0000470
7777	KCOL = 6	LA0000480
	DO 1002 ICOL = 7, 72	LA0000490
	IF (NWORDS(ICOL) - NBLANK) 1001, 1002, 1001	LA0000500
1001	KCOL = KCOL + 1	LA0000510
	NWORDS(KCOL) = NWORDS(ICOL)	LA0000520
1002	CONTINUE	LA0000530
	IF (NWORDS(6) - NBCD(11)) 777, 776, 777	LA0000540
776	IF (NQUIT) 500, 14, 100	LA0000550
14	ICOL = 6	LA0000560
	IF (M1) 500, 109, 19	LA0000570
777	NQUIT = 0	LA0000580
	M1 = 1	LA0000590
	DO 24 ICOL = 1, 5	LA0000600
	IF (NWORDS(ICOL) - NBLANK) 21, 24, 21	LA0000610
21	DO 23 LTYPE = 1, 4	LA0000620
	IF (NWORDS(ICOL) - KLABEL(LTYPE)) 23, 17, 23	LA0000630
23	CONTINUE	LA0000640
	GO TO 104	LA0000650
24	CONTINUE	LA0000660
	IF (KCOL - 6) 500, 1125, 125	LA0000670
1125	M3 = 4	LA0000680
	GO TO 305	LA0000690
104	ITRANS = 1	LA0000700
	GO TO 126	LA0000710
109	ITRANS = 2	LA0000720
126	CALL ECA04	LA0000730
	GO TO (500, 500, 500, 100, 110, 110), ITRANS	LA0000740
125	CALL ECA06	LA0000750

GO TO (5, 500, 46, 100, 110, 110), ITRANS	LA000760
46 IF (NOEXEC) 500, 5004, 4667	LA000770
5004 IF (IRTN = 1) 5006, 5006, 5005	LA000780
5005 GO TO (136, 137, 138), NTR	LA000790
5006 MAC = 0	LA000800
47 MAC=MAC+1	LA000810
MACFLO = KTYPE(MAC)	LA000820
GO TO (210, 210, 214, 216, 219, 220, 220, 238, 226, 228, 230),	LA000830
1 MACFLO	LA000840
210 NNODE = HNODE	LA000850
DO 3000 K=1,NNODE	LA000860
DO 2999 L = 1, NMAX	LA000870
IF (NINIT(L) = K) 2998, 3000, 2998	LA000880
2998 IF (NFIN(L) = K) 2999, 3000, 2999	LA000890
2999 CONTINUE	LA000900
NOEXEC=NOEXEC+1	LA000910
WRITE (6, 3001) K	LA000920
3000 CONTINUE	LA000930
DO 3205 K = 1, NMAX	LA000940
IF (MODE1 (K)) 3205, 3202, 3205	LA000950
3202 WRITE (6, 3003) K	LA000960
NOEXEC=NOEXEC+1	LA000970
3205 CONTINUE	LA000980
IRTN = 1	LA000990
IF(NOEXEC)500,5005,4667	LA001000
C	LA001010
C	LA001020
4667 WRITE (6, 2390)	LA001030
WRITE (6, 778) NOEXEC	LA001040
GO TO 219	LA001050
136 RETURN	LA001060
137 IF(OMEGA)1390,1390,1370	LA001070
1370 RETURN	LA001080
138 IF(DELTA)1381,1381,1380	LA001090
1381 IF(NEQUIM)1390,1390,1382	LA001100

1382 DELTA = 1.E-6	LA001110
1380 RETURN	LA001120
1390 WRITE(6,1301)	LA001130
1391 FORMAT(/ / 624 FREQUENCY OR TIME STEP IS IMPROPERLY DEFINED FOR THIS	LA001140
1 PROBLEM / /)	LA001150
NOEXEC=NOEXEC+1	LA001160
GO TO 4667	LA001170
214 IF (NEQUIN) 500, 210, 218	LA001180
218 TRADE = SHORT	LA001190
SHORT = OPEN	LA001200
OPEN = TRADE	LA001210
GO TO 210	LA001220
216 GO TO (94, 95, 500), NTR	LA001230
94 IRTN=3	LA001240
GO TO 136	LA001250
95 IRTN = 3	LA001260
GO TO 137	LA001270
220 WRITE (6, 231)	LA001280
219 MAC=0	LA001290
MO = 0	LA001300
WRITE (6, 702)	LA001310
GO TO 100	LA001320
44 ISEQ = 0	LA001330
NTRACE = 0	LA001340
NEQUIN = 0	LA001350
WRITE (6, 702)	LA001360
GO TO 47	LA001370
226 CALL USER01	LA001380
GO TO 44	LA001390
228 CALL USER02	LA001400
GO TO 44	LA001410
230 CALL USER03	LA001420
GO TO 44	LA001430
238 CALL EXIT	LA001440
	LA001450
	LA001460

C
C

C		LA001470
C		LA001480
	231 FORMAT (// 25H ILLEGAL INPUT STATEMENT,//)	LA001490
	778 FORMAT(1X,13,25H ERROR(S) WERE DETECTED,)	LA001500
	2390 FORMAT(40H INPUT ERRORS MAKE EXECUTION IMPOSSIBLE,)	LA001510
	3001 FORMAT(//9H NODE NO,14,13H IS MISSING,//)	LA001520
	3003 FORMAT(//11H BRANCH NO,14,13H IS MISSING,//)	LA001530
	500 ITRANS = 5	LA001540
	GO TO 110	LA001550
	805 ITRANS = 6	LA001560
	GO TO 110	LA001570
	1000 ITRANS = 7	LA001580
	NOUIT=0	LA001590
	110 CALL ECA07	LA001600
	GO TO 100	LA001610
	17 ITRANS = 1	LA001620
	GO TO 1713	LA001630
	19 ITRANS = 2	LA001640
	1713 CALL ECA02	LA001650
	GO TO (500, 500, 1313, 100, 110, 110), ITRANS	LA001660
	1313 GO TO (1314,1314,1315,1315,1315,1315,1315,1315,1314), INVAL	LA001670
	1314 CALL ECA03	LA001680
	GO TO 1316	LA001690
	1315 CALL ECA05	LA001700
	1316 GO TO (500, 1713, 1713, 100, 110, 110), ITRANS	LA001710
	5 CALL ECA06	LA001720
	GO TO 100	LA001730
	700 FORMAT(72A1)	LA001740
	701 FORMAT (1H 72A1)	LA001750
C		LA001760
	END	LA001770
	SUBROUTINE ECA09	LA090000
	DOUBLE PRECISION ACCUM	LA090010
C		LA090020
C	NUMERICAL EXTRACTION SUBROUTINE FOR INTERPRETING BCD NUMERALS INTO	LA090030
C	F, I, OR E DECIMAL FORMATS,	LA090040

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C          LA090050
        DIMENSION LIST4(200),LABEL(200),LISTE(5),LISTI(5),NUME(5),NUMI(5) LA090060
        DIMENSION LINK1D(200),LINK1E(200) LA090070
C          LA090080
        COMMON/MYS/MYSYS AD090010
        COMMON NMAX,NNODE,NTERMS,NUMBL,NUMBR,NUMBC,IRTN,NTRACE,MSWTCB,KTO,LA090090
1  MPPINT(10) LA090100
        COMMON E(200),ENIN(200),EMAX(200),AMP(200),AMPMIN(200),AMPMAX(200) LA090110
        COMMON Y(200),YMIN(200),YMAX(200),NINIT(200),NFIN(200),MODE1(200) LA090120
        COMMON YTERM(200),YTERMH(200),YTERML(200),IROWT(200),ICOLT(200) LA090130
        COMMON ERRGR1,ISEQ,MSEQ,MO,NUMNO,VFIRST(50),VSECON(50),VLAST(50) LA090140
        COMMON MOREN(50),MOPAR(50),MOPSTP(50),IWCOU(4),NLTRMS,DELTA LA090150
        COMMON IROWM(50),ICOLM(50),FLML(50),FLMH(50),FLM(50),EPHA(200), LA090160
1  AMPPHA(200),NREC,MAJOR,ERROR2,ERROR3,ETIME(5,2),ATIME(5,2) LA090170
        COMMON ETR(5,125),AMPTH(5,126) LA090180
C          LA090190
C          THE FOLLOWING VARIABLES ARE USED ONLY IN THE ECAP LANGUAGE PROG. LA090200
C          LA090210
        COMMON NWORDS(72),NMCP(2,20),KLABEL(4),KPUNC(5),INDC(2,20) LA090220
        COMMON INPUTR(9),NGCD(20),KTYPE(5),NBLANK,NOEXEC,ITOL,NEQUIM,IPC LA090230
        COMMON INVAL,LL,ICOL,LTYPE,KCOL,NOUIT,ITRANS,KC,KS,KELAST,NUM,M1 LA090240
        COMMON M2,M3,KCARD,KG,NP,NTN,MAC,HNODE,TNUM,NOEL,NOE,NOI,NOIC LA090250
        COMMON EQUIVH(20),KOUT(2,10) LA090260
C          LA090270
        EQUIVALENCE (YTERM(1),LIST4(1)),(ISEQ,START),(MSEQ,FINISH), LA090280
1  (NUMNO,SHORT),(VFIRST(2),LABEL(1)),(IWCOU(2),KE),(IWCOU(3),K1),LA090290
2  (IWCOU(4),NOBW),(DELTA,ONEHA),(FLM(1),LISTE(1)), LA090300
3  (FLM(6),LISTI(1)),(FLI(11),NUME(1)),(FLM(16),NUMI(1)), LA090310
4  (EPHA(1),LINK1D(1)),(AMPPHA(1),LINK1E(1)),(VFIRST(1),OPEN) LA090320
C          LA090330
C          LA090340
1  IF ( NTRACE ) 3, 4, 3 LA090350
2  FORMAT ( 41H LANG EXTRAC SUBR-PCA-09 ENTERED. ICOL=I4 ) LA090360
3  WRITE(6, 2) ICOL LA090370
4  TNUM = 0.0 LA090380
   KOUNT = 0 LA090390

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        MINUS=0
        MINUSE=0
        NPART=0
        NE = 0
        NGOE=0
        ACCUM = 0.000
        GO TO 101
100 ICOL = ICOL + 1
    IF ( ICOL - KCOL ) 101, 101, 35
101 DO 77 KEY = 1, 20
    IF ( NWORDS( ICOL ) - NPOD( KEY ) ) 77, 22, 77
77 CONTINUE
    M3 = 23
    GO TO 432
22 IF(KEY-3) 100, 6, 9
6 IF(NGOE) 500, 7, 3
7 MINUS=1
    GO TO 100
8 MINUSE=1
    GO TO 100
9 IF(KEY-14) 12,18, 10
12 IF(NGOE) 500, 185, 33
18 NPART = 1
    GO TO 100
10 IF(KEY-16) 21, 35, 35
185 IF(NPART) 500, 187, 186
186 KOUNT = KOUNT + 1
187 ACCUM = ACCUM *1.D1 + (KEY - 4)
    GO TO 100
21 NGOE = 1
    GO TO 100
33 NE = NE * 10 + (KEY - 4)
    GO TO 100
35 IF(MINUSE) 500, 40, 39
500 M3 = 1
432 NQUIT = 1

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LA090400
LA090410
LA090420
LA090430
LA090440
LA090450
LA090460
LA090470
LA090480
LA090490
LA090500
LA090510
LA090520
LA090530
LA090540
LA090550
LA090560
LA090570
LA090580
LA090590
LA090600
LA090610
LA090620
LA090630
LA090640
LA090650
LA090660
LA090670
LA090680
LA090690
LA090700
LA090710
LA090720
LA090730
LA090740
LA090750

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      GO TO 43
39  NE = - NE
40  NE = NE - KOUNT
      IF ( NE ) 27, 28, 27
27  ACCUM = ACCUM * 1.D1*NE
28  TNUM = ACCUM
      IF (MINUS) 36, 43, 36
36  TNUM = - TNUM
43  ICOL = ICOL - 1
9996  CONTINUE
      GO TO (99962,99961,99961,99962,99962), MYSYS
99961 IF (INVAL.NE.7) GO TO 99962
      IF (KONCE.EQ.1) GO TO 99963
      AUXL=TNUM
      TNUM=1./AUXL
      KONCE=1
      GO TO 99962
99963 KONCE=0
99962 IF ( NTRACE ) 9998, 9999, 9998
9997 FORMAT(41H LANG EXTRAC SUBR-ECA-09 EXIT.          ICOL=14,
1      8H      TNUM=E15.3 )
9998 WRITE(6, 9997) ICOL,TNUM
9999 RETURN
      END

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LA090760
LA090770
LA090780
LA090790
LA090800
LA090810
LA090820
LA090830
LA090840
LA090845
AD090020
AD090030
AD090040
AD090050
AD090060
AD090070
AD090080
AD090090
LA090050
LA090060
LA090070
LA090080
LA090090
LA090900

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SUBROUTINE ECA25
DOUBLE PRECISION X(200)
COMMON/MYS/MYSYS
COMMON NMAX,NNODE,NTERMS,NUHBL,NUMBR,NUMBC,IRTN,NTRACE,NSWTC,KT0,
1 NPRINT(10)
COMMON E(200),EMIN(200),EMAX(200),AMP(200),AMPMIN(200),AMPMAX(200)
COMMON Y(200),YMIN(200),YMAX(200),NINIT(200),NFIN(200),MODE1(200)
COMMON YTERM(200),YTERMH(200),YTERML(200),IPORT(200),ICOLT(200)
COMMON ERROR1,ISFQ,MSFQ,NO,NUMNO,VFIRST(50),VSECND(50),VLAST(50)
COMMON MOPRN(50),MOPARM(50),MOSTEP(50),IWCOUT(4)

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DC250000
DC250010
AD250010
DC250020
DC250030
DC250040
DC250050
DC250060
DC250070
DC250080

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C		DC250090
C	THE FOLLOWING VARIABLES ARE USED ONLY IN THE ECAP D.C. ANALYSIS	DC250100
C		DC250110
	COMMON AX1,SMLEP(50),CURR(200),SMLE(200),EQUCUR(50),EX(200)	DC250120
	COMMON EB(200),AMPX(200),AMPR(200),VNON(50),STLSQ(50),L,M,ITOL	DC250130
	COMMON JX1,JX4,JX5,DELTA,DUM1(25)	DC250140
C		DC250150
	COMMON LANG(265)	DC250160
C		DC250170
	COMMON MATA(200,4,3),YX(200),YR(200),YTERMX(200),YTERMB(200)	DC250180
	COMMON WCMAX(50),WCMIN(50)	DC250190
C		DC250200
	DOUBLE PRECISION SMLEP,CURR,SMLE,EQUCUR	DC250210
C		DC250220
	1 IF(NTRACE)3,4,3	DC250230
	2 FORMAT(6H FCA25)	DC250240
	3 WRITE(6,2)	DC250250
	4 IF(JX4)8,5,101	DC250260
C		DC250270
C	OUTPUT NODE VOLTAGES	DC250280
C		DC250290
	8 IF(NPRINT(1))101,101,99	DC250300
99	WRITE(6,133)	DC250310
99	GO TO (1000,2000,3000,3001,3002),MYSYS	AD250020
1000	WRITE(6,133)	AD250030
	WRITE(6,134)	DC250320
	133 FORMAT(// 14H NODE VOLTAGES //)	DC250330
	134 FORMAT(6H NODES,15X,3HVOLTAGES /)	DC250340
	GO TO 4000	AD250040
2000	WRITE(6,1133)	AD250050
1133	FORMAT(// ' NODE VELOCITIES' //, ' NODES',15X,'VELOCITIES' /)	AD250060
	GO TO 4000	AD250070
3000	WRITE(6,2133)	AD250080
	GO TO 4000	AD250090
3001	WRITE(6,3113)	AD250100
	GO TO 4000	AD250110

3002	WRITE(6,4113)	AD250120
2133	FORMAT(// ' ANGULAR VELOCITIES AT NODES' ,//, ' NODES' ,15X,	AD250130
	1 'VELOCITIES'//)	AD250140
3113	FORMAT(// ' NODE TEMPERATURES' ,//, ' NODES' ,15X, 'TEMPERATURES'//)	AD250150
4113	FORMAT(// ' NODE PRESSURES' ,//, ' NODES' ,15X, 'PRESSURES'//)	AD250160
4000	CONTINUE	AD250170
	DO 5 I=1,NNODE	DC250350
5	X(I)=SMLEP(I)	DC250360
	KMAX=NNODE	DC250370
	IND=1	DC250380
	GO TO 100	DC250390
C		DC250400
C	BRANCH VOLTAGES	DC250410
C		DC250420
101	DO 10 I=1,NMAX	DC250430
	SMLE(I) = 0.0	DC250440
	J=NINIT(I)	DC250450
	IF(J)11,11,12	DC250460
12	SMLE(I) = SMLEP(J)	DC250470
11	K=NEJN(I)	DC250480
	IF (K) 10, 10, 14	DC250490
14	SMLE(I) = SMLE(I) - SMLEP(K)	DC250500
10	CONTINUE	DC250510
	IF(JX4)9,9,102	DC250520
	IF(NPRINT(5))102,102,15	DC250530
15	WRITE(6,131)	DC250540
15	GO TO(5000,6000,7000,7001,7002),NYSYS	AD250180
5000	WRITE(6,131)	AD250190
	WRITE(6,132)	DC250550
131	FORMAT(// 16H BRANCH VOLTAGES //)	DC250560
132	FORMAT(9H BRANCHES,12X,6HVOLTAGES//)	DC250570
	GO TO 8000	AD250200
6000	WRITE(6,1131)	AD250210
1131	FORMAT(//, ' BRANCH VELOCITIES' ,//, ' BRANCHES' ,12X, 'VELOCITIES'//)	AD250220
7000	WRITE(6,2131)	AD250230
2131	FORMAT(//, ' BRANCH ANGULAR VELOCITIES' ,//, ' BRANCHES' ,12X,	AD250240

1	'VELOCITIES'//	AD250250
	GO TO 8000	AD250260
7001	WRITE(6,3131)	AD250270
3131	FORMAT(//,' BRANCH TEMPERATURES',//,' BRANCHES',12X,	AD250280
1	'TEMPERATURES'//	AD250290
	GO TO 8000	AD250300
7002	WRITE(6,4131)	AD250310
4131	FORMAT(//,' BRANCH PRESSURES',//,' BRANCHES',12X,'PRESSURES'//)	AD250320
8000	CONTINUE	AD250330
	DO 16 I=1,NMAX	DC250340
16	X(I)=SMLE(I)	DC250350
	KMAX=NMAX	DC250360
	JUD=2	DC250370
	GO TO 100	DC250380
C		DC250390
C	ELEMENT VOLTAGES	DC250400
C		DC250410
102	DO 17 I=1,NMAX	DC250420
17	SMLE(I)=SMLE(I)+EX(I)	DC250430
	IF(JX4)7,7,103	DC250440
7	IF(MPRINT(3))103,103,13	DC250450
10	WRITE(6,135)	DC250460
13	GO TO (9000,10000,11000,11001,11002),MYSYS	AD250340
9000	WRITE(6,135)	AD250350
	WRITE(6,132)	DC250710
135	FORMAT(// 17H ELEMENT VOLTAGES//)	DC250720
	GO TO 12000	AD250360
10000	WRITE(6,1135)	AD250370
1135	FORMAT(//,' ELEMENT VELOCITIES'// ' PATHS',12X,'VELOCITIES'//)	AD250380
	GO TO 12000	AD250390
11000	WRITE(6,2135)	AD250400
2135	FORMAT(//,' ELEMENT ANGULAR VELOCITIES'//,' BRANCHES',12X,	AD250410
1	'VELOCITIES'//)	AD250420
	GO TO 12000	AD250430
11001	WRITE(6,3135)	AD250440
3135	FORMAT(//,' ELEMENT TEMPERATURES',//,' BRANCHES',12X,	AD250450

1	'TEMPERATURES'//)	AD250460
	(0 TO 12000	AD250470
11002	WRITE(6,4135)	AD250480
4135	FORMAT(//,' ELEMENT PRESSURES',//,' BRANCHES',12X,'PRSSSURES'//)	AD250490
12000	CONTINUE	AD250500
	DO 19 I=1,NMAX	DC250730
19	X(I)=SMLE(I)	DC250740
	KMAX=NMAX	DC250750
	IAU=3	DC250760
	GO TO 100	DC250770
C		DC250780
C	ELEMENT CURRENTS	DC250790
C		DC250800
103	DO 20 I=1,NMAX	DC250810
20	CURR(I)=YX(I)*SMLE(I)	DC250820
	IF(NTERMS)21,22,21	DC250830
21	DO 22 I=1,NTERMS	DC250840
	NR=IPONT(I)	DC250850
	NC=ICOLT(I)	DC250860
	IF(SMLE(NC))24,23,24	DC250870
24	CURR(NR)=CURR(NR)+YTERM(X(I)*SMLE(NC)	DC250880
23	CONTINUE	DC250890
22	IF(JX4)25,25,105	DC250900
25	IF(NPPINT(2))104,104,26	DC250910
26	WRITE(6,136)	DC250920
26	GO TO (1300,1400,1500,1501,1502),MYSYS	AD250510
1300	WRITE(6,136)	AD250520
	WRITE(6,137)	DC250930
136	FORMAT(// 174 ELEMENT CURRENTS //)	DC250940
137	FORMAT(9H BRANCHES,12X,8ECURRENTS/)	DC250950
	GO TO 1600	AD250530
1400	WRITE(6,1136)	AD250540
1136	FORMAT(//,' ELEMENT FORCES'//,' PATHS',12X,'FORCES'//)	AD250550
	GO TO 1600	AD250560
1500	WRITE(6,2136)	AD250570
2136	FORMAT(//,' ELEMENT TORQUES',//,' BRANCHES',12X,' TORQUES'//)	AD250580


```

      GO TO 1600
1511 WRITE(6,3136 )
3136 FORMAT(//,' ELEMENT HEAT FLOW',//,' BRANCHES',12X,'HEAT FLOW'/)
      GO TO 1600
1502 WRITE(6,4136)
4136 FORMAT(//,' ELEMENT VOLUME VELOCITIES',//,' BRANCHES',12X,
1 'VOLUME VELOCITIES'/)
1600 CONTINUE
      DO 27 I=1,NMAX
27 X(I)=CURR(I)
      KMAX=NMAX
      IND=4
      GO TO 100

C
C   BRANCH POWER LOSSES
C
104 IF(NPRINT(6))105,105,28
28 DO 29 I=1,NMAX
29 X(I)=CURR(I)*SNLE(I)
1700 WRITE(6,138)
      WRITE(6,139)
138 FORMAT(// 21H ELEMENT POWER LOSSES //)
139 FORMAT( 9H BRANCHES,12X,12HPOWER LOSSES/)
      KMAX=NMAX
      IND=3
      GO TO 100

C
C   BRANCH CURRENTS
C
105 DO 30 I=1,NMAX
30 CURR(I)=CURR(I)-AMPX(I)

C
C   CHECK UNBALANCES
C
      DO 33 I=1,NNODE
33 X(I)=0.

```

```

AU250590
A7250600
AD250610
AU250620
AD250630
AD250640
AD250650
AD250660
DC250960
DC250970
DC250980
DC250990
DC251000
DC251010
DC251020
DC251030
DC251040
DC251050
DC251060
DC251070
DC251080
DC251090
DC251100
DC251110
DC251120
DC251130
DC251140
DC251150
DC251160
DC251170
DC251180
DC251190
DC251200
DC251210
DC251220
DC251230

```

```

      DO 36 I=1,NMAX
      J=RNINT(I)
      K=RFIN(J)
      IF(K)34,34,35
35  X(K)=X(K)+CURR(I)
34  IF(J)36,36,37
37  X(J)=X(J)-CURR(I)
36  CONTINUE
      SUM=0.
      DO 38 I=1,NNODE
38  SUM = SUM + DABS( X( I ))
      IF(SUM-ERROR1)106,106,40
40  WRITE(6,141)
2100 WRITE (6,142)
141  FORMAT( // 43H SOLUTION NOT OBTAINED TO DESIRED TOLERANCE//)
142  FORMAT( 6H NODES,15X,19H CURRENT UNBALANCES /)
      KMAX=NNODE
      IND=6
      GO TO 100
106  IF(JX4)300,300,900
300  IF(NPRINT(4))900,900,41
41  DO 42 I=1,NMAX
42  X(I)=CURR(I)
      GO TO(2500,2600,2700,2701,2702),MYSYS
2500  WRITE(6,140)
      WRITE(6,137)
140  FORMAT(// 16H BRANCH CURRENTS//)
      GO TO 2800
2600  WRITE(6,1140)
      GO TO 2800
1140  FORMAT(//' BRANCH FORCES',//,' BRANCHES',12X,'FORCES'//)
2700  WRITE(6,2140)
2140  FORMAT (//,' BRANCH TORQUES',//,' BRANCHES',12X,'TORQUES'//)
      GO TO 2800
2701  WRITE(6,3140)
3140  FORMAT(//' BRANCH HEAT FLOW',//,' BRANCHES',12X,'HEAT FLOW'//)

```

```

DC251240
DC251250
DC251260
DC251270
DC251280
DC251290
DC251300
DC251310
DC251320
DC251330
DC251340
DC251350
DC251360
DC251370
DC251380
DC251390
DC251400
DC251410
DC251420
DC251430
DC251440
DC251450
DC251460
AD250670
DC251470
DC251480
DC251490
AD250680
AD250690
AD250700
AD250710
AD250720
AD250730
AD250740
AD250750
AD250760

```

GO TO 2800	AD250770
2702 WRITE(6,4140)	AD250780
4140 FORMAT(//,' BRANCH VOLUME VELOCITIES',//,' BRANCHES',12X,	AD250790
1 'VELOCITIES',//)	AD250800
2800 CONTINUE	AD250810
KMAX=KMAX	DC251500
IMP=7	DC251510
C	DC251520
C OUTPUT ROUTINE	DC251530
C	DC251540
100 LAST=0	DC251550
150 K=LAST+1	DC251560
LAST=LAST+4	DC251570
IF(LAST-KMAX)200,200,201	DC251580
201 LAST=KMAX	DC251590
200 WRITE(6,203)K,LAST,(X(J),J=K,LAST)	DC251600
203 FORMAT(1X,I3,1F7.13,2X,4(3X,E15.5))	DC251610
IF(KMAX-LAST)500,500,150	DC251620
C	DC251630
500 GO TO (101,102,103,104,105,41,200),IMP	DC251640
200 RETURN	DC251650
END	DC251660
 SUBROUTINE ECA51(IA)	AC510000
DIMENSION POWRL(200)	AC510010
C	AC510020
COMMON/MYS/MYSYS	AD510010
COMMON NMAX,NNODE,NTERMS,NUMBL,NUMBR,NUMBC,IRTN,NTRACE,NSWITCH,KTO,	AC510030
1 NPRINT(10)	AC510040
COMMON E(200),EMIN(200),EMAX(200),AMP(200),AMPMIN(200),AMPMAX(200)	AC510050
COMMON Y(200),YMIN(200),YMAX(200),NINIT(200),NFIN(200),MODE1(200)	AC510060
COMMON YTERM(200),YTERPH(200),YTERPL(200),IRONT(200),ICOLT(200)	AC510070
COMMON ERROR1,ISEG,MSEG,MO,NUXMO,VFIRST(50),VSFCORP(50),VLAST(50)	AC510080
COMMON POWRN(50),MOPARN(50),MOTIER(50),INCOLT(4),ALTRMS,OMEGA	AC510090
COMMON IPORN(50),ICOLA(50),FLBL(50),FLPH(50),FLN(50),EPHA(200)	AC510100
COMMON AMPPHA(200),NREC	AC510110

C		AC510120
C	THE FOLLOWING VARIABLES ARE USED ONLY IN THE ECAP A.C. ANALYSIS	AC510130
C		AC510140
	COMMON EQUCL(50),EQUCLIM(50),CIN(200),ELIM(200),EPPL(50),EPIM(50)	AC510150
	COMMON FLMSAV(25),IRSAV(25),IUSAV(25),HNODE,CVOLT(200),OMGINV	AC510160
	COMMON DELTA,ITOL,LL,ITRANS,DUMX(2)	AC510170
C		AC510180
	COMMON LANG(265)	AC510190
C		AC510200
	COMMON ELSAV(200),CVOLTR(200),CAMPRL(200),CAMPIM(200)	AC510210
C		AC510220
	DOUBLE PRECISION EQUCL,EQUCLIM,EPRL,EPIM,CVOLT,CVOLTR,CAMPRL,	AC510230
	1 CAMPIM	AC510240
	DOUBLE PRECISION EPIM(200),EBRL(200),BAMPRL(200),BAMPIM(200)	AC510250
	EQUIVALENCE (EQUCL(1),POWER(1)),(CVOLT(1),EBIN(1)),	AC510260
	1 (CVOLTR(1),EBRL(1)),(CAMPRL(1),BAMPRL(1)),	AC510270
	2 (CAMPIM(1),BAMPIM(1))	AC510280
1	IF(NTRACE)2,4,2	AC510290
2	WRITE(6,3) IA	AC510300
3	FORMAT(' ECAP1 ENTERED. IA=',I3)	AC510310
4	IF (IA - 1) 1000,552,1000	AC510320
	552 IF(NPRINT(1)+NPRINT(2)+NPRINT(3)+NPRINT(4)+NPRINT(5)+NPRINT(6)	AC510330
	1 +NPRINT(10))511,1000,511	AC510340
511	FREQ = OMEGA/6.283185	AC510350
	WRITE(6,525) FREQ	AC510360
525	FORMAT(//,' FREQ =',E16,8)	AC510370
1000	IF(IA-11)1001,30,1001	AC510380
1001	IF(NPRINT(IA))7,500,7	AC510390
7	GO TO (21,22,23,24,25,26,27,28,29),IA	AC510400
100	FORMAT(/// 7X 5HNODES, 10X 14H NODE VOLTAGES ///	AC510410
101	FORMAT(/// 4X 8HBRANCHES 10X 17H ELEMENT CURRENTS ///	AC510420
102	FORMAT(/// 4X 8HBRANCHES 10X 17H ELEMENT VOLTAGES ///	AC510430
103	FORMAT(/// 4X 8HBRANCHES 10X 16H BRANCH CURRENTS ///	AC510440
104	FORMAT(/// 4X 8HBRANCHES 10X 16H BRANCH VOLTAGES ///	AC510450
105	FORMAT(/// 4X 8HBRANCHES 10X 16H BRANCH POWER ///	AC510460

106	FORMAT(/// 1X 24H SENSITIVITIES NOT CALC. ///	AC510470
107	FORMAT(/// 1X 21H WORST-CASE NOT CALC. ///	AC510480
108	FORMAT(/// 1X 20H STD. DEV. NOT CALC. ///	AC510490
109	FORMAT(///, ' SOLUTION NOT OBTAINED TO DESIRED TOLERANCE',//)	AC510500
110	FORMAT(7X,5HNODES,10X,19H CURRENT UNBALANCES,/))	AC510510
21	WRITE (6, 100)	AC510520
	GO TO 500	AC510530
22	WRITE (6, 101)	AC510540
	GO TO 500	AC510550
23	WRITE (6, 102)	AC510560
	GO TO 500	AC510570
24	WRITE (6, 103)	AC510580
	GO TO 500	AC510590
25	WRITE (6, 104)	AC510600
	GO TO 500	AC510610
26	WRITE (6, 105)	AC510620
	GO TO 500	AC510630
2100	FORMAT(///,7X,'NODES',10X,'VELOCITIES AT NODES',//)	AD510620
3100	FORMAT(///,7X,'NODES' ,10X,'NODE ANGULAR VELOCITIES'//)	AD510630
4100	FORMAT(///,7X,'NODES',10X,'NODE TEMPERATURES'//)	AD510640
5100	FORMAT(///,7X,'NODES',10X,'NODE PRESSURES'//)	AD510650
2101	FORMAT(///,7X,'BRANCHES',7X,'FORCES DEVELOPED IN ELEMENTS',//)	AD510660
3101	FORMAT(///,4X,'BRANCHES',10X,'ELEMENT TORQUES'//)	AD510670
4101	FORMAT(///,4X,'BRANCHES',10X,'ELEMENT HEAT FLOWS'//)	AD510680
5101	FORMAT(///,4X,'BRANCHES',10X,'ELEMENT VOLUME VELOCITIES'//)	AD510690
2102	FORMAT(///,4X,'BRANCHES',10X,'ELEMENT VELOCITIES'//)	AD510700
3102	FORMAT(///,4X,'BRANCHES',10X,'ELEMENT ANGULAR VELOCITIES'//)	AD510710
4102	FORMAT(///,4X,'BRANCHES',10X,'ELEMENT TEMPERATURES'//)	AD510720
5102	FORMAT(///,4X,'BRANCHES',10X,'ELEMENT PRESSURES'//)	AD510730
2103	FORMAT(///,4X,'BRANCHES',10X,' BRANCH FORCES'//)	AD510740
3103	FORMAT(///,4X,'BRANCHES',10X,' BRANCH TORQUES'//)	AD510750
4103	FORMAT(///,4X,'BRANCHES',10X,' BRANCH HEAT FLOWS'//)	AD510760
5103	FORMAT(///,4X,'BRANCHES',10X,' BRANCH VOLUME VELOCITIES'//)	AD510770
2104	FORMAT(///,4X,'BRANCHES',10X,'BRANCH VELOCITIES'//)	AD510780
3104	FORMAT(///,4X,'BRANCHES',10X,' BRANCH ANGULAR VELOCITIES'//)	AD510790

4104	FORMAT(///,4X,'BRANCHES',10X,' BRANCH TEMPERATURES'//)	AD510200
5104	FORMAT(///,4X,'BRANCHES',10X,' BRANCH PRESSURES'//)	AD510210
21	GO TO (121,221,321,421,521),MYSYS	AD510220
121	WRITE(6,100)	AD510230
	GOTO500	AD510240
221	WRITE(6,2100)	AD510250
321	WRITE(6,3100)	AD510260
	GOTO500	AD510270
421	WRITE(6,4100)	AD510280
	GO TO 500	AD510290
521	WRITE(6,5100)	AD510300
	GO TO 500	AD510310
22	GO TO (122,222,322,422,522),MYSYS	AD510320
122	WRITE(6,101)	AD510330
	GOTO500	AD510340
222	WRITE(6,2101)	AD510350
	GOTO500	AD510360
322	WRITE(6,3101)	AD510370
	GOTO500	AD510380
422	WRITE(6,4101)	AD510390
	GO TO 500	AD510400
522	WRITE(6,5101)	AD510410
	GO TO 500	AD510420
23	GO TO (123,223,323,423,523),MYSYS	AD510430
123	WRITE(6,102)	AD510440
	GOTO500	AD510450
223	WRITE(6,2102)	AD510460
	GOTO500	AD510470
323	WRITE(6,3102)	AD510480
	GOTO500	AD510490
423	WRITE(6,4102)	AD510500
	GO TO 500	AD510510
523	WRITE(6,5102)	AD510520
	GO TO 500	AD510530
24	GO TO (124,224,324,424,524),MYSYS	AD510540

124	WRITE(6,103)	AD510550
	GO TO 500	AD510560
224	WRITE(6,2103)	AD510570
	GO TO 500	AD510580
324	WRITE(6,3103)	AD510590
	GO TO 500	AD510600
424	WRITE(6,4103)	AD510610
	GO TO 500	AD510620
	GO TO 500	AD510630
524	WRITE(6,5103)	AD510640
	GO TO 500	AD510645
25	GO TO (125,225,325,425,525),MYSYS	AD510650
125	WRITE(6,104)	AD510660
	GO TO 500	AD510670
225	WRITE(6,2104)	AD510680
	GO TO 500	AD510690
325	WRITE(6,3104)	AD510700
	GO TO 500	AD510710
425	WRITE(6,4104)	AD510720
	GO TO 500	AD510730
525	WRITE(6,5104)	AD510740
	GO TO 500	AD510750
27	WRITE (6, 106)	AD510640
	GO TO 500	AD510650
28	WRITE (6, 107)	AD510660
	GO TO 500	AD510670
29	WRITE (6, 108)	AD510680
	GO TO 500	AD510690
30	WRITE(6,109)	AD510700
	WRITE(6,110)	AD510710
500	IF(CTRACE)9997,9999,9997	AD510720
9997	WRITE(6, 9998)	AD510730
9998	FORMAT(1X 11H ECA51 EXIT)	AD510740
9999	RETURN	AD510750
	END	AD510760

	SUBROUTINE PRINT2	TR890000
C		TR890010
	DIMENSION X(200)	TR890020
C		TR890030
C		TR890040
	COMMON LINKS,NODES,NTERMS,NUMBL,NUMBR,NUMBC,IRTN,NTRACE,NSWITCH,	TR890050
	1 XTO,NPRINT(10)	TR890060
	COMMON/MYS/MYSYS	TR890070
	COMMON EO(200),BIAS1(200),BIAS2(200),AMPO(200),FLOW1(200)	TR890080
	COMMON FLOW2(200),Y(200),Y1(200),Y2(200),NT(200),NH(200)	TR890090
	COMMON HODE1(200),LIST4(200),YTERM2(200),YTERM1(200),IRJHT(200)	TR890100
	COMMON ICOLT(200),ERROR1,START,FINISH,NSTEP,SHORT,OPEN,LABEL(200)	TR890110
	COMMON R(50),KE,KI,LOCKS,ALTRDS,DELTA,TROW(50),ICOLM(50),FLM1(50)	TR890120
	COMMON FLN2(50),LISTE(5),LISTI(5),NOME(5),NUMI(5),JSTEP(10)	TR890130
	COMMON JSTEPS(10),JLINE(10),LINK1D(200),LINK1E(200),NREC,MAJOR	TR890140
	COMMON ERROR2,ERROR3,ETIME(5,2),ATIME(5,2),ETR(5,126),AMPTR(5,126)	TR890150
C		TR890160
	COMMON LANG(265)	TR890170
C		TR890180
C	THE FOLLOWING VARIABLES ARE USED ONLY BY TRANSIENT ANALYSIS	TR890190
C		TR890200
	COMMON V(50),VO(50),FLUX(200),VALUE(200),LEVER(200),LEVERS(200)	TR890210
	COMMON LINK1A(200),ITAB(10),ESLOPE(5),ASLOPE(5),HOLD	TR890220
	COMMON LEAST,LIST,LATCH,LOCK,LOCKA,LOCKR,LOCKD,LOCKE,LOCKG,MINDR	TR890230
	COMMON BUNKER,PARTS,SAVE,STEP,T,TEST,THIGH,FLOR,TSTAR,TZERO	TR890240
	COMMON UNIT,JAL	TR890250
C		TR890260
	DOUBLE PRECISION B,V,VO,FLUX,VALUE	TR890270
	1 IF(NTRACE) 3, 4, 3	TR890280
	2 FORMAT(7H PRINT2)	TR890290
3	WRITE(6, 2)	TR890300
4	IFR = 0	TR890310
	DO 5 I=1,6	TR890320
5	IFR = IFR + NPRINT(I)	TR890330
	IF (LOCKE) 8100, 500, 500	


```

500 IF(LOCK) 1000, 1007, 1000
1000 IF( JX1 ) 1001, 1001, 8000
1001 CALL SSWICH ( 1,LOST)
      GO TO ( 1004 , 1005 ), LOST
1003 IF( NPR ) 1005, 1005, 1004
1004 WRITE( 6, 10 ) T
10   FORMAT(///, '      T = ', E15.7, '/')
1005 GO TO ( 1008, 1007 ), LOST
1007 IF( NPRINT(1)) 1010, 1010, 1008
1008 WRITE (6, 11 )
11   FORMAT(/, ' NODES', 15X, 'NODE VOLTAGES',/)
1008 GOTO (11008,21008,31008,41008,51008),NYSYS
11008 WRITE(6,11)
      GO TO 61008
21008 WRITE(6,211)
      GO TO 61008
31008 WRITE(6,311)
      GO TO 61008
41008 WRITE(6,411)
      GO TO 61008
51008 WRITE(6,511)
61008 CONTINUE
      LIMIT=NODES
      JX2 = 1
      DO 1009 I = 1, NODES
1009  X(I) = V(I)
      GO TO 9010
1010 IF( NPRINT(5)+LPRINT(6)+NPRINT(3))1023,1023,1011
1011 DO 1015 I = 1, LINKS
      J = NT(I)
      IF(J)1013,1013,1012
1012 X(I) = V(J)
1013 J= RH(I)
      IF( J ) 1015,1015,1014
1014 X(I)=X(I) - V(J)

```

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TR890340
TR890350
TR890360
TR890370
TR890380
TR890390
TR890400
TR890410
TR890420
TR890430
TR890440
AD890020
AD890030
AD890040
AD890050
AD890060
AD890070
AD890080
AD890090
AD890100
AD890110
AD890120
TR890450
TR890460
TR890470
TR890480
TR890490
TR890500
TR890510
TR890520
TR890530
TR890540
TR890550
TR890560
TR890570

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1015 CONTINUE
      IF ( NPRINT( 5 )) 1018, 1013, 1016
1016 GO TO (11016,21016,31016,41016,51016),MYSYS
11016 WRITE(6,1017)
      GO TO 61016
21016 WRITE(6,21017)
      GO TO 61016
31016 WRITE(6,31017)
      GO TO 61016
41016 WRITE(6,41017)
      GO TO 61016
51016 WRITE(6,51017)
61016 CONTINUE
      1015 WRITE( 6, 1017 )
      1017 FORMAT(/,' BRANCHES',12X,'BRANCH VOLTAGES',/)
      LIMIT = LINKS
      JX2 = 2
      GO TO 9010
      1018 IF( NPRINT(6) + NPRINT(3)) 1023, 1023, 1019
      1019 DO 1020 I = 1, LINKS
      1020 X(I) =X(I)+ BJAS1(I)
      IF(NPRINT(3))1023,1023,1021
      1021 JX2=3
      LIMIT=LINKS
      WRITE(6,1022)
      GO TO (190,290,390,490,590),MYSYS
190  WRITE(6,1022)
      GO TO 9010
290  WRITE(6,21022)
      GO TO 9010
390  WRITE(6,31022)
      GO TO 9010
490  WRITE(6,41022)
      GO TO 9010
590  WRITE(6,51022)

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TR890580
TR890590
AD890130
AD890140
AD890150
AD890160
AD890170
AD890180
AD890190
AD890200
AD890210
AD890220
AD890230
TR890580
TR890610
TR890620
TR890630
TR890640
TR890650
TR890660
TR890670
TR890680
TR890690
TR890700
TR890710
AD890240
AD890250
AD890260
AD890270
AD890280
AD890290
AD890300
AD890310
AD890320
AD890330

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1022	FORMAT(/,' BRANCHES',12X,'ELEMENT VOLTAGES',/)	TR890720
	GO TO 9010	TR890730
1023	GO TO (1026, 1025), LOST	TR890740
1025	IF (NPRINT(2)) 1027, 1027, 1026	TR890750
1026	WRITE(6, 30)	TR890760
1026	GO TO (11026,21026,31026,41026,51026),MYSYS	A0890340
11026	WRITE(6,30)	AD890350
	GO TO 61026	AD890360
21026	WRITE(6,230)	AD890370
	GO TO 61026	AD890380
31026	WRITE(6,330)	AD890390
	GO TO 61026	AD890400
41026	WRITE(6,430)	AD890410
	GO TO 61026	AD890420
51026	WRITE(6,530)	AD890430
61026	CONTINUE	AD890440
30	FORMAT(/,' BRANCHES',12X,'ELEMENT CURRENTS', /)	TR890770
	JX2 = 4	TR890780
	LIMIT = LINKS	TR890790
	GO TO 9010	TR890800
1027	IF (NPRINT(6)) 1031, 1031, 1028	TR890810
1028	DO 1029 I = 1, LINKS	TR890820
1029	X(I) = X(I) * FLUX(I)	TR890830
	WRITE(6, 1030)	TR890840
1030	FORMAT(/,' BRANCHES',12X,'INSTANTANEOUS ELEMENT POWER',/)	TR890850
	JX2 = 5	TR890860
	LIMIT = LINKS	TR890870
	GO TO 9010	TR890880
1031	IF(NPRINT(4)) 3000, 8000, 1032	TR890890
1032	DO 1033 I = 1, LINKS	TR890900
1033	X(I) = FLUX(I) - FLOW1(I)	TR890910
	WRITE(6, 1034)	TR890920
	GO TO (191,291,391,491,591),MYSYS	AD890450
191	WRITE(6,1034)	AD890460
	GO TO 691	AD890470

291	WRITE(6,21034)	ADR90480
	GO TO 691	ADR90490
391	WRITE(6,31034)	ADR90500
	GO TO 691	ADR90510
491	WRITE(6,41034)	ADR90520
	GO TO 691	ADR90530
591	WRITE(6,51034)	ADR90540
691	CONTINUE	ADR90550
1034	FORMAT(/,' BRANCHES',12X,'BRANCH CURRENTS',/)	TR890930
	JX2 = 6	TR890940
	LIMIT = LINKS	TR890950
9010	LAST = 0	TR890960
9011	K = LAST + 1	TR890970
	LAST = LAST + 4	TR890980
	IF (LAST - LIMIT) 9013, 9013, 9012	TR890990
9012	LAST = LIMIT	TR891000
9013	IF(JX2 - 4) 9014, 9015, 9014	TR891010
9014	WRITE(6,9016) K, LAST, (X(J), J = K, LAST)	TR891020
	GO TO 9017	TR891030
9015	WRITE(6,9016) K, LAST, (FLUX(J), J = K, LAST)	TR891040
9017	IF (LIMIT - LAST) 9016, 9018, 9011	TR891050
9018	GO TO (1010, 1010, 1023, 1027, 1031, 9000), JX2	TR891060
9016	FORMAT(1X,13,'-',13,2X,4(3),E15.8)	TR891070
8000	IF (LOCKF) 9000, 9000, 8100	TR891080
8100	DO 8400 N = 1, LIST	TR891090
	M = LEVER(N)	TR891100
	LATCH = LABEL(M)	TR891110
	GO TO (8200, 8250), LATCH	TR891120
8200	LABEL(N) = 2	TR891130
	WRITE(6,90) N	TR891140
90	FORMAT(/,' SWITCH',13,' IS ON')	TR891150
	GO TO 8400	TR891160
8250	LABEL(N) = 1	TR891170
	WRITE(6,91) N	TR891180
91	FORMAT(/,' SWITCH',13,' IS OFF')	TR891190

```

6400 CONTINUE
      GO TO ( 8500, 8600 ), LOCKP
8500 LOCKB = 2
      GO TO 8700
8600 DELTA = HOLD - ( T - TSTAR )
8700 LOCK = 1
      LOCKF = 0
211  FORMAT(/,' NODES',15X,'NODE VELOCITIES',/)
311  FORMAT(/,' NODES',15X,'ANGULAR VELOCITIES AT NODES',/)
411  FORMAT(/,' NODES',15X,'TEMPERATURES AT NODES',/)
511  FORMAT(/,' NODES',15X,'NODE PRESSURES',/)
230  FORMAT(/,' BRANCHES',12X,'ELEMENT FORCES',/)
330  FORMAT(/,' BRANCHES',12X,'ELEMENT TORQUES',/)
430  FORMAT(/,' BRANCHES',12X,'ELEMENT HEAT FLOWS',/)
530  FORMAT(/,' BRANCHES',12X,'ELEMENT VOLUME VELOCITIES',/)
21034 FORMAT(/,' BRANCHES',12X,'FORCES IN BRANCHES',/)
31034 FORMAT(/,' BRANCHES',12X,'TORQUES IN BRANCHES',/)
41034 FORMAT(/,' BRANCHES',12X,'HEAT FLOW IN BRANCHES',/)
51034 FORMAT(/,' BRANCHES',12X,'VOLUME VELOCITY IN BRANCHES',/)
21017 FORMAT(/,' BRANCHES',12X,'BRANCH VELOCITIES',/)
31017 FORMAT(/,' BRANCHES',12X,'BRANCH ANGULAR VELOCITIES',/)
41017 FORMAT(/,' BRANCHES',12X,'BRANCH TEMPERATURES',/)
51017 FORMAT(/,' BRANCHES',12X,'BRANCH PRESSURES',/)
21022 FORMAT(/,' BRANCHES',12X,'ELEMENT VELOCITIES',/)
31022 FORMAT(/,' BRANCHES',12X,'ELEMENT ANGULAR VELOCITIES',/)
41022 FORMAT(/,' BRANCHES',12X,'ELEMENT TEMPERATURES',/)
51022 FORMAT(/,' BRANCHES',12X,'ELEMENT PRESSURES',/)
9000 RETURN
      END

```

```

TR891200
TR891210
TR891220
TR891230
TR891240
TR891250
TR891260
AD890560
AD890570
AD890580
AD890590
AD890600
AD890610
AD890620
AD890630
AD890640
AD890650
AD890660
AD890670
AD890680
AD890690
AD890700
AD890710
AD890720
AD890730
AD890740
AD890750
AD890760
TR891270
TR891280

```

APPENDIX D

Sample Problems and UHSAP Solutions

```

MECHANICAL SYSTEM PROBLEM
C
C      EXAMPLE # 1
C
C      DYNAMIC ANALYSIS PROBLEM
C

```

```

      DYNAMIC ANALYSIS;
P1  N(1,0),K=2.E-3;
P2  N(1,0),B=8;
P3  N(1,2),K=2.E-3;
P4  N(1,2),B=4.0E-3;
P5  N(2,0),K=10,V=6;
      TIME STEP=1.0E-1;
      OUTPUT INTERVAL=10;
      FINAL TIME=1.0E+2;
      PRINT,VELOCITIES,FORCES;
      EXECUTE;
      STOP;

```

I = 0.0

NODES VELOCITIES AT NODES

1- 2 -0.23998658E-03 -0.59997097E-01

BRANCHES FORCES DEVELOPED IN ELEMENTS

1- 4 -0.23998658E-03 -0.23998652E-01 0.59995180E-06 0.23998662E-01
 5- 5 0.23998662E-01

T = .9999996 00

NODES VELOCITIES AT NODES

1- 2 -0.65345168E-02 -0.59947233E 01

BRANCHES FORCES DEVELOPED IN ELEMENTS

1- 4 -0.14466856D-04 -0.71896759D-01 0.47958497D-01 0.23952739D-01
5- 5 0.71911236D-01

T = .1999994E 01

NODES VELOCITIES AT NODES

1- 2 -0.18602162E-01 -0.59849052E 01

BRANCHES FORCES DEVELOPED IN ELEMENTS

1- 4 -0.75350897D-04 -0.11957174D 00 0.95792696D-01 0.23864395D-01
5- 5 0.11964709D 00

T = .2999989E 01

NODES VELOCITIES AT NODES

1- 2 -0.37037090E-01 -0.59757204E 01

BRANCHES

FORCES DEVELOPED IN ELEMENTS

1- 4	-0.21243407D-03	-0.16690820D 00	0.14338737D 00	0.23733262D-01
5- 5	0.16712833D 00			

F = .3999983E 01

NODES

VELOCITIES AT NODES

1- 2	-0.61039105E-01	-0.59510193E 01
------	-----------------	-----------------

BRANCHES

FORCES DEVELOPED IN ELEMENTS

1- 4	-0.45528317D-03	-0.21379164D 00	0.19068726D 00	0.23559665D-01
5- 5	0.21424692D 00			

F = .4999977E 01

NODES

VELOCITIES AT NODES

1- 2	-0.91013730E-01	-0.59270229E 01
------	-----------------	-----------------

BRANCHES

FORCES DEVELOPED IN ELEMENTS

1- 4	-0.83317837D-03	-0.26010267D 00	0.23759783D 00	0.23344020D-01
5- 5	0.26094185D 00			

T = .5949971E 01

NODES VELOCITIES AT NODES

1- 2 -0.12667257E 00 -0.58983841E 01

BRANCHES FORCES DEVELOPED IN ELEMENTS

1- 4 -0.13750424D-02 -0.30574726D 00 0.22403547D 00 0.23086830D-01
5- 5 0.30712230D 00

T = .6199966E 01

NODES VELOCITIES AT NODES

1- 2 -0.16793306E 00 -0.58651590E 01

BRANCHES FORCES DEVELOPED IN ELEMENTS

1- 4 -0.21073705D-02 -0.35059699D 00 0.32991767D 00 0.22788690D-01
5- 5 0.35270636D 00

T = .7299940E 01

NODES VELOCITIES AT NODES

1- 2 -0.21483322E 00 -0.58274126E 01

ANCHORS

FORCES DEVELOPED IN ELEMENTS

1- 4	-0.20641616D-02	-0.39454933D 00	0.37516321D 00	0.22450280D-01
5- 5	0.39751349D 00			

T = 0.8999954E 01

NODES

VELOCITIES AT NODES

1- 2	-0.26712143E 00	-0.57852163E 01
------	-----------------	-----------------

ANCHORS

FORCES DEVELOPED IN ELEMENTS

1- 4	-0.42658505D-02	-0.43749781D 00	0.41769229D 00	0.22072366D-01
5- 5	0.44176466D 00			

T = 0.9999749E 01

NODES

VELOCITIES AT NODES

1- 2	-0.32460720E 00	-0.57386503E 01
------	-----------------	-----------------

ANCHORS

FORCES DEVELOPED IN ELEMENTS

1- 4	-0.57442417D-02	-0.47933830D 00	0.46342675D 00	0.21655799D-01
5- 5	0.48508254D 00			

Example 2

The system shown in Figure P.2 is a mechanical translational system. It is required to determine the frequency response of the system for the applied alternating force f , by studying the forces developed in various elements for different frequencies of f .

UHSAP coding for the problem and the solution given by the program follows in next pages.

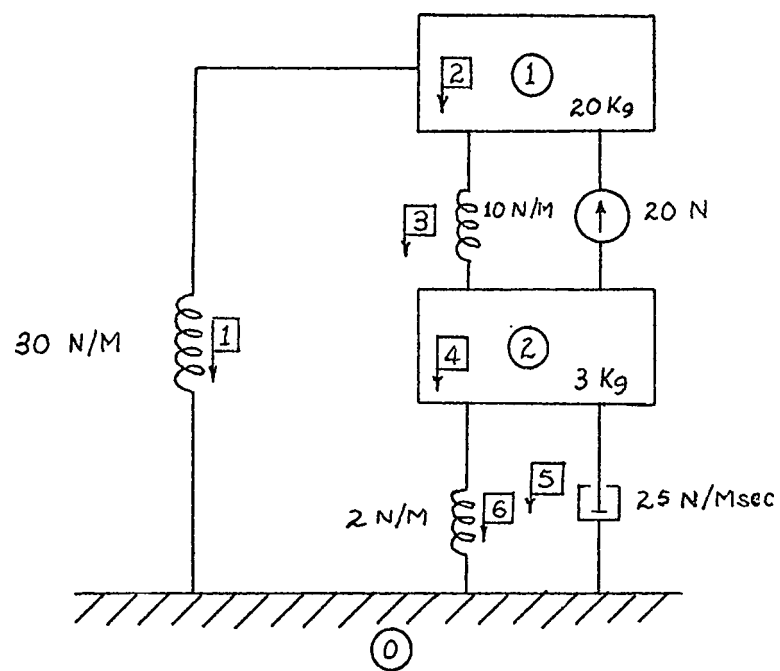


Fig. P. 2

MECHANICAL SYSTEM PROBLEM

C

C

EXAMPLE # 2

C

ALTERNATING FORCE ANALYSIS PROBLEM

C

FOR A MECHANICAL SYSTEM

C

AF ANALYSIS;

P1

M(1,0),K=30;

P2

N(1,0),M=20;

P3

M(2,0),K=2.0;

P3

N(1,2),K=10,F=20/0.;

P4

J(2,0),M=3.0;

P5

N(2,0),M=25.0;

FR=0.01;

PRINT,VELOCITIES,FORCES;

EX;

MODIFICATION # 1 FOR FREQUENCY RESPONSE;

FR=0.1(10)1000.;

EX;

FN;

1
F = 0.99999942E-02

NODES

VELOCITIES AT NODES

1- 2 0.82975067E-02 0.9793122E-01
0.11390637E 03 -0.99405029E 02

BRANCHES

FORCES DEVELOPED IN ELEMENTS

1- 4 0.39617691E 01 0.16425946E-01 0.16650848E 02 0.19469371E-01
0.28906372E 02 -0.15107355E 03 -0.65868254E 01 -0.74050503E 01

5- 6 0.24495773E 01 0.31169003E 01
-0.99405029E 02 0.17359489E 03

PLU = 0.99999905E-01

NODES VELOCITIES AT NODES

1- 2 0.35193288E 00 0.47457574E 00
0.11314388E 03 -0.15383361E 03

BRANCHES FORCES DEVELOPED IN ELEMENTS

1- 4 0.16803558E 02 0.44225159E 01 0.98947048E 01 0.93225235E 00
0.23143875E 02 -0.15685605E 03 -0.29459274E 02 -0.63883621E 02

2- 6 0.12364387E 02 0.15742826E 01
-0.15383361E 03 0.11511632E 03

PLU = 0.99999952E 00

NODES VELOCITIES AT NODES

1- 2 0.17242748E 00 0.67138332E 00
-0.87540009E 02 0.14551227E 03

BRANCHES FORCES DEVELOPED IN ELEMENTS

MAG 1- 4 0.82519078E 03 0.21715124E 02 0.12519941E 01 0.12655272E 02
 PUA -0.17753999E 03 0.24599609E 01 -0.13425359E 03 -0.12408765E 03

MAG 5- 6 0.16784576E 02 0.21370810E 00
 PUA 0.14591229E 03 0.55912277E 02

FLOW = 0.99799933 01

NODES VELOCITIES AT NODES

MAG 1- 2 0.15936779E-01 0.10530049E 00
 PUA -0.89793637E 02 0.77562531E 02

BRANCHES FORCES DEVELOPED IN ELEMENTS

MAG 1- 4 0.76092658E-02 0.20025749E 02 0.19276395E-01 0.19848648E 02
 PUA -0.17979367E 03 0.03134673E-02 -0.17342882E 03 -0.17243741E 03

MAG 5- 6 0.26325111E 01 0.33518702E-02
 PUA 0.97562531E 02 0.75625725E 01

FREQ = 0.99999927E 02

NODES VELOCITIES AT NODES

1- 2 0.15915723E-02 0.10609526E-01
-0.89999969E 02 0.90759827E 02

BRANCHES FORCES DEVELOPED IN ELEMENTS

1- 4 0.75992022E-04 0.20000259E 02 0.19418474E-03 0.19998459E 02
-0.17999995E 03 0.64152055E-05 -0.17932923E 03 -0.17924011E 03

5- 6 0.26523805E 00 0.33771168E-04
0.90759827E 02 0.75997220E 00

FREQ = 0.99999927E 02

NODES VELOCITIES AT NODES

1- 2 0.15915514E-03 0.10610335E-02
-0.89999969E 02 0.90759743E 02

BRANCHES

FORCES DEVELOPED IN ELEMENTS

MAG 1- 4 0.75991045E-03 0.20000000E-02 0.19419222E-05 0.19999969E-02
 P.A -0.17999995E-03 0.64162471E-03 -0.17993300E-03 -0.17992395E-03

MAG 5- 6 0.26525822E-01 0.33773756E-06
 P.A 0.90075974E-02 0.75990856E-01

FIELD = 0.9999983E-04

NODES

VELOCITIES AT NODES

MAG 1- 2 0.15915517E-04 0.10610346E-03
 P.A -0.809999959E-02 0.90007568E-02

BRANCHES

FORCES DEVELOPED IN ELEMENTS

MAG 1- 4 0.75991018E-08 0.20000000E-02 0.19419939E-07 0.19999985E-02
 P.A -0.17999995E-03 0.64162590E-11 -0.17999335E-03 -0.17999236E-03

MAG 5- 6 0.26525850E-02 0.33773768E-06
 P.A 0.90007568E-02 0.75990930E-12

Example 3.

Figure P.3 shows a mechanical rotational system. The angular velocity applied at one end varies with time and is of triangular shape. It is required to study the transient effect of this source to this system after the system is started from a resting position.

UHSAP coding for the problem and the program solutions are in next page.

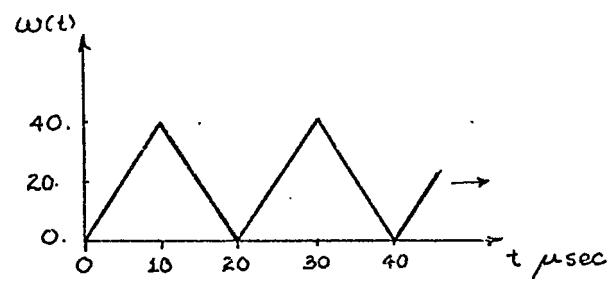
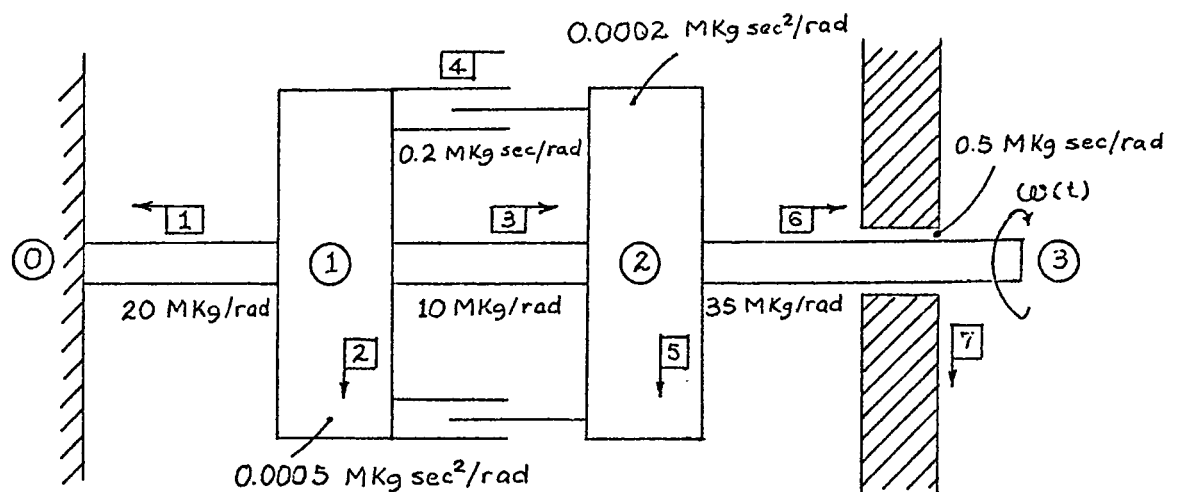


Fig. P.3

ROTATIONAL

C

C EXAMPLE # 3

C

C DYNAMIC ANALYSIS OF A

C ROTATIONAL SYSTEM WITH TIME VARIANT

C ANGULAR VELOCITY APPLIED AT ONE END

C

 DYNAMIC ANALYSIS;

P1 N(1,0),K=20;

P2 N(1,0),J=5E-4;

P3 N(1,2),K=10.;

P4 N(1,2),J=0.2;

P5 N(2,0),J=2E-4;

P6 N(2,3),K=35;

P7 N(3,0),B=0.5;

W7 P(5) ,0.,20.,40.,20.,0. ;

 TIME STEP=1E-6 ;

 OUTPUT INTERVAL=10;

 FINAL TIME=1E-4;

 PRINT ,ANGULAR VELOCITIES,TORQUES;

 EX;

 EN;

T = 0.0

NODES ANGULAR VELOCITY AT NODES

1- 3 0.0 0.0 0.0

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 0.0 0.0 0.0 0.0
5- 7 0.0 0.0 0.0 0.0

T = 0.9999994E-05

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.16874941E-05 -0.13430273E-03 -0.39935901E 02

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.74900199D-11 -0.26830336D-04 0.35475933D-03 0.26826795D-04
5- 7 -0.69715012D-02 0.69933315D-02 0.69933315D-02

T = 0.1999996E-04

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.19112531E-05 -0.72900451E-03 0.28066780E-01

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.17452842D-09 -0.14564261D-03 0.44130439D-07 0.14559866D-02
5- 7 -0.13844355D-01 0.13989999D-01 0.13989998D-01

$$T = 0.2999989E-04$$

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.65014792E-05 -0.15523736E-02 -0.39957870E 02

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.96128597D-09 -0.30932822D-03 0.15474781D-06 0.30917443D-03
5- 7 -0.20668806D-01 0.20978136D-01 0.20978136D-01

$$T = 0.3999982E-04$$

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.15391200E-04 -0.28288364E-02 0.56081839E-01

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.30641003D-08 -0.56305824D-03 0.37027281D-06 0.56269103D-03
5- 7 -0.27396316D-01 0.27959377D-01 0.27959377D-01

$$T = 0.4999975E-04$$

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.29785922E-04 -0.43249428E-02 -0.39929871E 02

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.74824352D-08 -0.85974714D-03 0.72270868D-06 0.85903192D-03
5- 7 -0.34077106D-01 0.34936861D-01 0.34936861D-01

T = 0.5999969E-04

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.51119365E-04 -0.62679090E-02 0.84053814E-01

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.15444268D-07 -0.12445888D-02 0.12457449D-05 0.12433583D-02
5- 7 -0.40662617D-01 0.41907221D-01 0.41907221D-01

T = 0.6799962E-04

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.80579426E-04 -0.84234662E-02 -0.39901932E-02

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.28473140D-07 -0.16705203D-02 0.17710131D-05 0.16685778D-02
5- 7 -0.47203050D-01 0.48873599D-01 0.48873599D-01

T = 0.7999755E-04

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.11953272E-03 -0.11013906E-01 0.11198092E-00

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.48313635D-07 -0.21827577D-02 0.29308431D-05 0.21798752D-02
5- 7 -0.53649826D-01 0.55832632D-01 0.55832632D-01

T = 0.8999948E-04

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.16914043E-03 -0.13820048E-01 -0.39874023E 02

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.76998517D-07 -0.27342601D-02 0.41555186D-05 0.27301816D-02
5- 7 -0.60053126D-01 0.62787464D-01 0.62787464D-01

T = 0.9999941E-04

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.23073291E-03 -0.17054256E-01 0.13986140E 00

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.11677430D-06 -0.33702653D-02 0.56770331D-05 0.33647051D-02
5- 7 -0.66364352D-01 0.69734734D-01 0.69734734D-01

T = 0.1009994E-03

NODES ANGULAR VELOCITY AT NODES

1- 3 -0.23760376E-03 -0.17386075E-01 -0.38600082E 01

BRANCHES TORQUE DEVELOPED IN ELEMENTS

1- 4 -0.12145766D-06 -0.34354200D-02 0.58468930D-05 0.34276945D-02
5- 7 -0.66363692D-01 0.69797234D-01 0.69797234D-01

Example 4*

This example has been considered to show the validity of the results of UHSAP analysis with those by analytical methods.

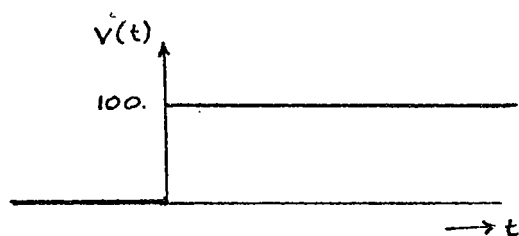
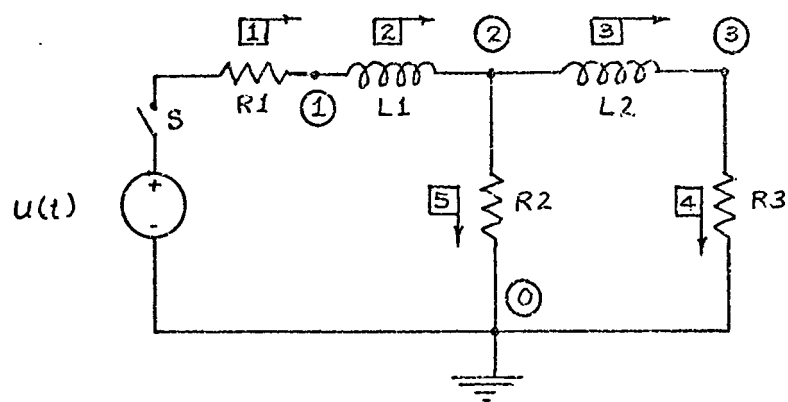
Consider the electrical circuit in Figure P.4. The switch S is closed at time $t = 0$ and the transient current in the resistor R3 at time $t = t$ is given by

$$i(t) = 3.33 - 5e^{-10t} + 1.67e^{-30t}$$

The numerical results given by this expression at different value of t are tabulated in Figure P4.1 and UHSAP results which are in the following pages for actual comparison.

Figure P4.2 shows the computed values with both the methods.

* Adapted from Ref. 1, pages 159-160.



$$R_1 = 10 \Omega$$

$$L_1 = 1 \text{ H}$$

$$R_2 = 10 \Omega$$

$$L_2 = 1 \text{ H}$$

$$R_3 = 10 \Omega$$

Fig P.4

ELECTRICAL SYSTEM

C

C EXAMPLE # 4

C

TR

C

B1 N(0,1),R=10,E=100

B2 N(1,2),L=1

B3 N(2,3),L=1

B4 N(3,0),R=10

B5 N(2,0),R=10

TI=0.001

DU=20

FI=0.2

PRINT, CURRENTS

EX

LN

T = 0.0

BRANCHES

ELEMENT CURRENTS

1-	4	0.99999766D-05	0.99999766D-05	0.99999567D-11	0.99999567D-11
5-	5	0.99999666D-05			

T = 0.1999997E-01

BRANCHES

ELEMENT CURRENTS

1-	4	0.16583812D 01	0.16583812D 01	0.15433260D 00	0.15433260D 00
5-	5	0.15040486D 01			

T = 0.3999994E-01

BRANCHES		ELEMENT CURRENTS			
1-	4	0.28131364D 01	0.28131364D 01	0.48369116D 00	0.48369116D 00
5-	5	0.23294452D 01			

T = 0.5999990E-01

BRANCHES		ELEMENT CURRENTS			
1-	4	0.36471636D 01	0.36471636D 01	0.86475150D 00	0.86475150D 00
5-	5	0.27824121D 01			

T = 0.7999963E-01

BRANCHES		ELEMENT CURRENTS			
1-	4	0.42688687D 01	0.42688687D 01	0.12378743D 01	0.12378743D 01
5-	5	0.30309945D 01			

T = 0.9999937E-01

BRANCHES		ELEMENT CURRENTS			
1-	4	0.47443255D 01	0.47443255D 01	0.15769123D 01	0.15769123D 01
5-	5	0.31674132D 01			

T = 0.1199991E 00

BRANCHES		ELEMENT CURRENTS			
1-	4	0.51151833D 01	0.51151833D 01	0.18729054D 01	0.18729054D 01
5-	5	0.32422780D 01			

T = 0.1399989E 00

BRANCHES		ELEMENT CURRENTS			
1-	4	0.54087110D 01	0.54087110D 01	0.21253481D 01	0.21253481D 01
5-	5	0.32833628D 01			

T = 0.1599986E 00

BRANCHES		ELEMENT CURRENTS			
1-	4	0.56434854D 01	0.56434854D 01	0.23375757D 01	0.23375757D 01
5-	5	0.33059096D 01			

T = 0.1799983E 00

BRANCHES		ELEMENT CURRENTS			
1-	4	0.58326589D 01	0.58326589D 01	0.25143759D 01	0.25143759D 01
5-	5	0.33182830D 01			

T = 0.1999981E 00

BRANCHES

ELEMENT CURRENTS

1- 4	0.59858708D 01	0.59858708D 01	0.26607974D 01	0.26607974D 01
5- 5	0.33250734D 01			

T = 0.2009981E 00

BRANCHES

ELEMENT CURRENTS

1- 4	0.59927258D 01	0.59927258D 01	0.26674083D 01	0.26674083D 01
5- 5	0.33253175D 01			

TIME	CURRENT IN BRANCH NO. 4
0.0	-0.95367432D-06
0.20000000D-01	0.15286110
0.39999999D-01	0.48139375
0.59999999D-01	0.86199072
0.79999998D-01	1.2348540
0.99999998D-01	1.5737470
0.12000000	1.8696594
0.14000000	2.1220577
0.16000000	2.3342610
0.18000000	2.5110481
0.20000000	2.6574630

Figure P4.1

TIME	CURRENT IN BRANCH NO.4	
	USAF VALUE	ANALYTICAL VALUE
0.00	0.00	0.00
0.02	0.1543	0.1528
0.04	0.4836	0.4814
0.06	0.8647	0.8620
0.08	1.2379	1.2348
0.10	1.5770	1.5737
0.12	1.8729	1.8696
0.14	2.1253	2.1221
0.16	2.3375	2.3342
0.18	2.5148	2.5110
0.20	2.6607	2.6574

Figure P4.2